

Using FIT/CorteXlab for the Evaluation of Access Policies in Dense IoT Networks through S3CAP, a New Modular Framework

GRCOn 2022

Amaury Paris, Leonardo S. Cardoso, Jean-Marie Gorce

INSA de Lyon, INRIA, CITI Lab

September 29, 2022

INSA



Multiple access in IoT

- IoT projections: the number of devices will more than double in the next years.
- Big problem to solve: huge number of devices sending very small packets in the uplink
- ALOHA-style medium access policies will become less viable for crowded IoT networks
- Collisions and re-transmissions: increased latency, higher energy consumption and shorter device battery life
- Going beyond simulations: inaccurate capture of interference patterns - real transmissions and repeatability

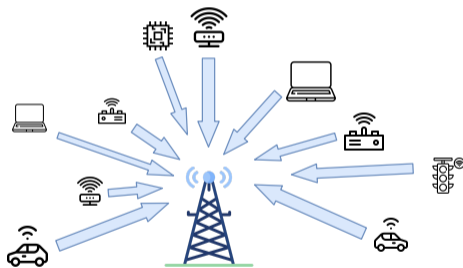
Multiple access in IoT

- IoT projections: the number of devices will more than double in the next years.
- Big problem to solve: huge number of devices sending very small packets in the uplink
- ALOHA-style medium access policies will become less viable for crowded IoT networks
- Collisions and re-transmissions: increased latency, higher energy consumption and shorter device battery life
- Going beyond simulations: inaccurate capture of interference patterns - real transmissions and repeatability
- Our response to this need: Slotted-Synchronized multi-Source framework for experimentation on Channel Access Policies

S3-CAP framework

S3-CAP framework

- **Channel access policies**
Development and evaluation of new channel access policies
- **Robust coding at the transmitter**
Study of interference, non-orthogonal communication, error-correcting systems
- **Improved multi-level receiver**
Successive interference cancellation, joint decoding



Presentation Outline

- 1 FIT/CorteXlab testbed
- 2 Framework implementation
- 3 Usage

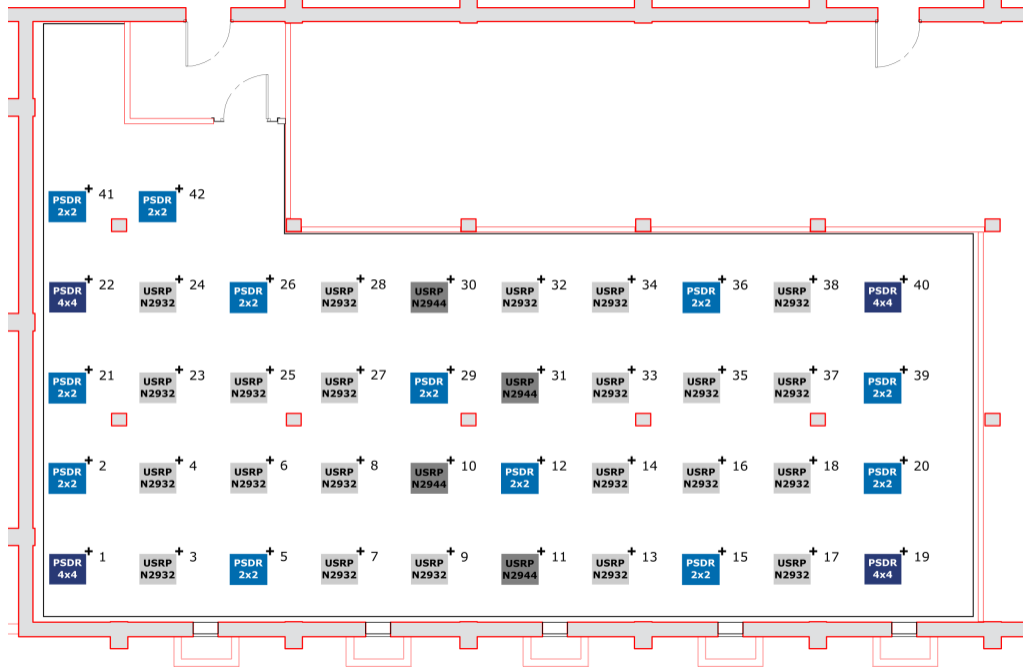
FIT/CorteXlab testbed

FIT/CorteXlab

- Future Internet of Things - COgnitive Radio Testbed and EXperimentation LAB
- 180m² shielded and semi-anechoized experimentation room: at least 60dB isolation
- 40 software defined radios among USRPs and PicoSDRs, all GNU Radio compatible
- Reproducible experiments: stable propagation environment exempt from outside interference
- Dockerized operation: any version of GNU Radio can be used (as well as any other UHD based code)
- Octoclocks: full synchronization of USRPs is possible
- **Free to use** and remotely accessible over the internet (<https://wiki.cortexlab.fr>)



Figure: USRP NI-2932, USRP N2944R, PicoSDR, Octoclock





Opportunities with FIT/CorteXlab

- Research! Test your multi-radio techniques and architectures in FIT/CorteXlab
- Teaching: Radio, propagation, etc.. lab sessions (during confinements)
- Learn GNU Radio and USRP operation autonomously: GNU Radio's or CorteXlab's tutorials
- Automated test for validation of UHD and GNU Radio code on actual hardware
- Any other usage you may think of...

S3_CAP framework

Framework Layout

Uplink channel access

- Access policies;
- Robust coding.

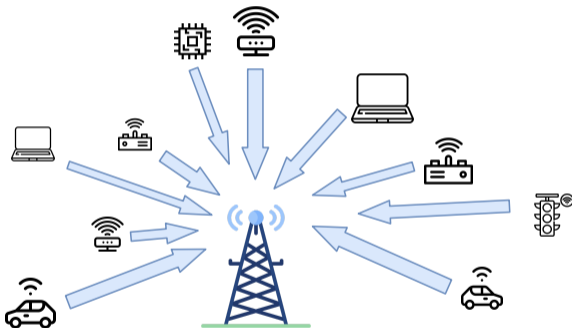


Figure: A star system

Framework Layout

Uplink channel access

- Access policies;
- Robust coding.

RF uplink channel

- Time framed;
- Slotted.

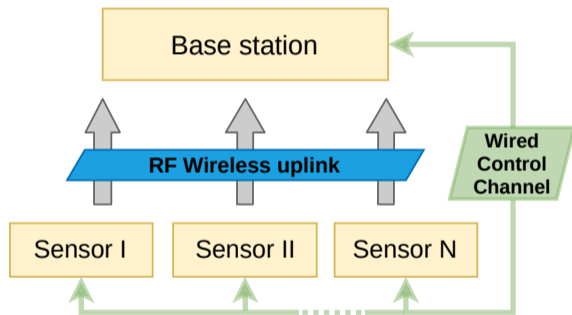


Figure: A star system

Framework Layout

Uplink channel access

- Access policies;
- Robust coding.

RF uplink channel

- Time framed;
- Slotted.

Wired control channel

- Uplink;
- Downlink;
- Error-free.

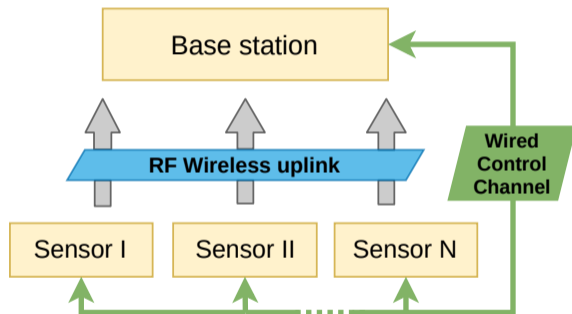


Figure: A star system

Framework Layout

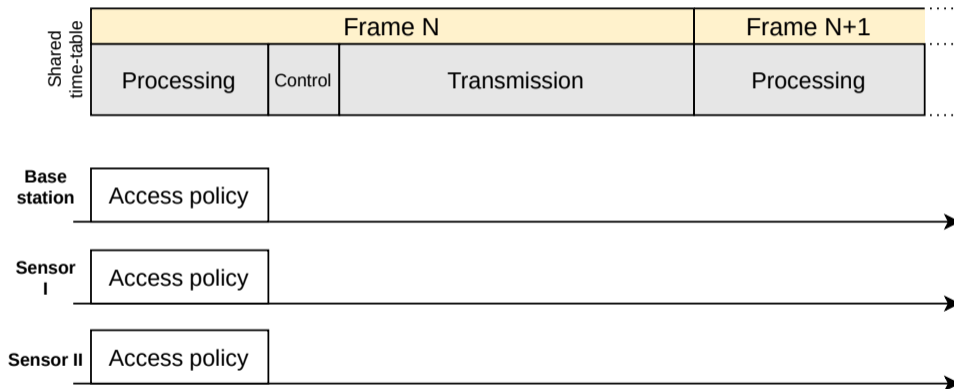


Figure: Shared time table

Framework Layout

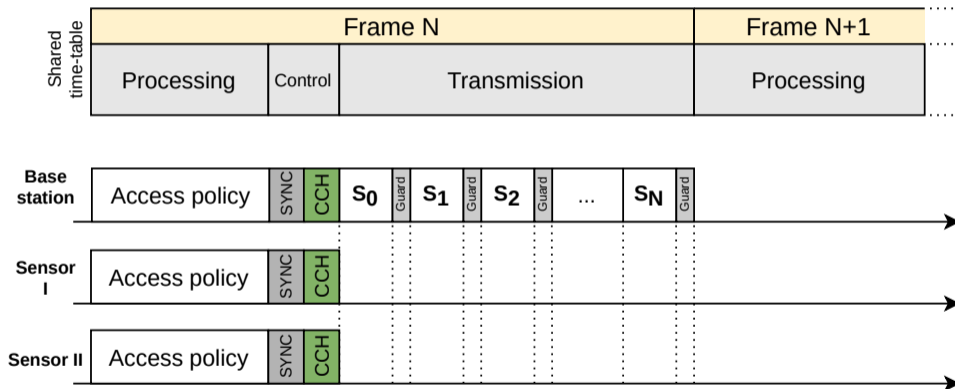


Figure: Shared time table

Framework Layout

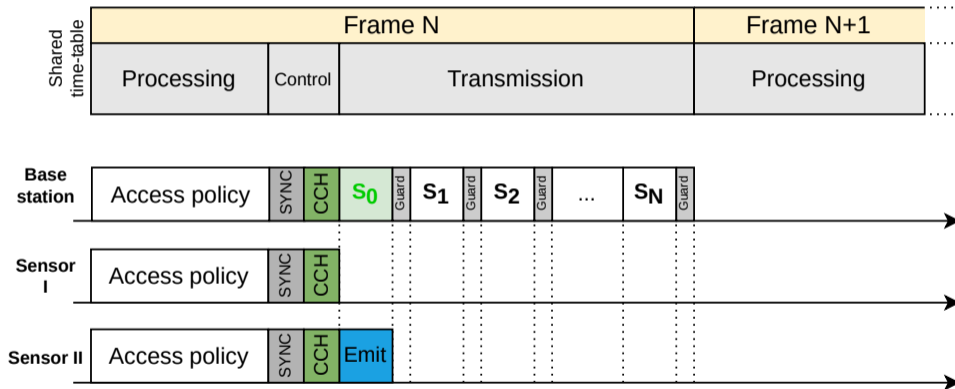


Figure: Shared time table

Framework Layout

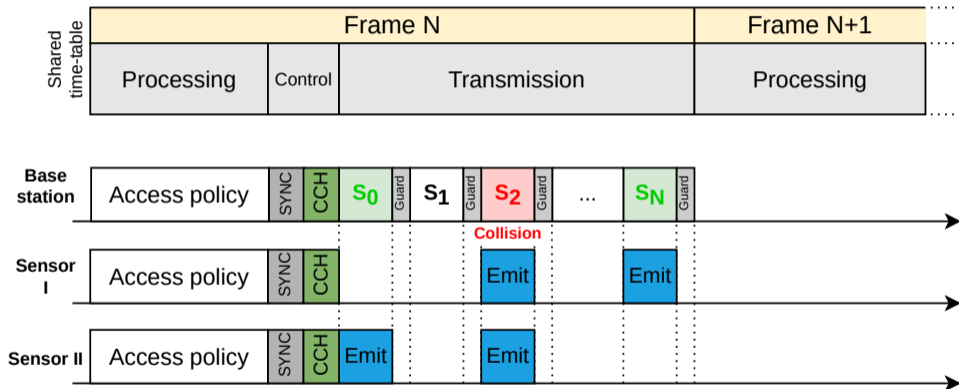


Figure: Shared time table

Framework Layout

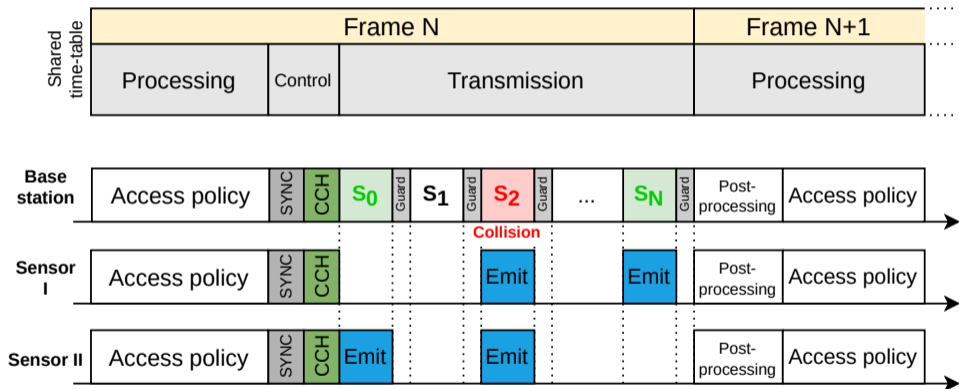


Figure: Shared time table

Adaptive implementation

Implement MAC layer in
GNU Radio

- Time consuming;
- Unnecessarily difficulty.

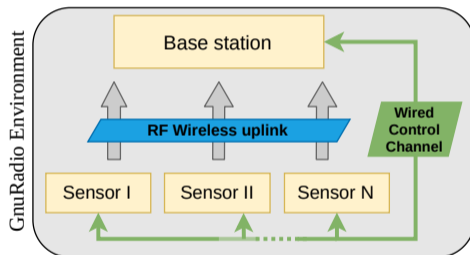


Figure: Access policy implementation

Adaptive implementation

Implement MAC layer in
GNU Radio

- Time consuming;
- Unnecessarily difficulty.

External implementation

- Centralized;

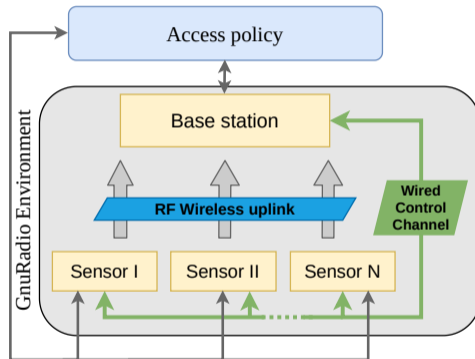


Figure: Access policy implementation

Adaptive implementation

Implement MAC layer in
GNU Radio

- Time consuming;
- Unnecessarily difficulty.

External implementation

- Centralized;
- Decentralized.

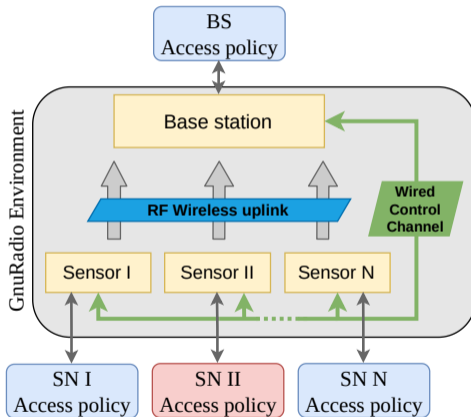


Figure: Access policy implementation

Adaptive implementation

Implement MAC layer in
GNU Radio

- Time consuming;
- Unnecessarily difficulty.

External implementation

- Centralized;
- Decentralized.

Distributed implementation

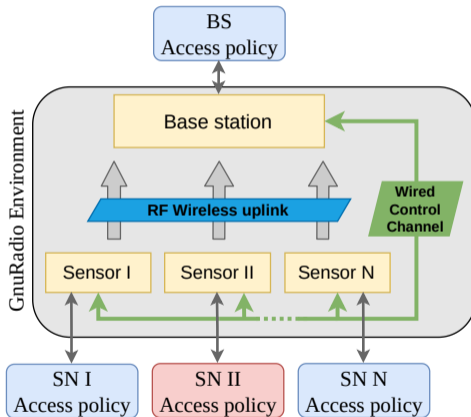


Figure: Access policy implementation

Adaptive implementation

Implement MAC layer in
GNU Radio

- Time consuming;
- Unnecessarily difficulty.

External implementation

- Centralized;
- Decentralized.

Distributed implementation

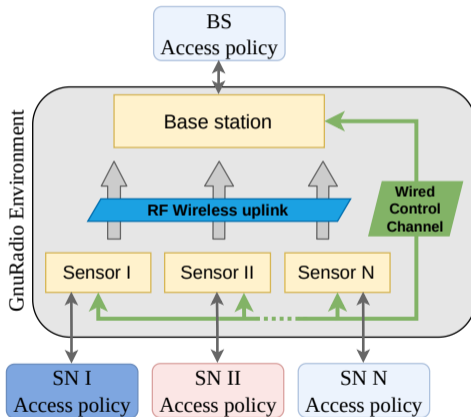


Figure: Access policy implementation

Dummy access policy

```
up = upper()

while True:
    pp = up.extract(up.recv())
    print("SN : %s, Frame : %s" % (pp["NODE"], pp["FRAME"]))

    if pp["DLCCH"] == "GR_Con_22":
        inst = up.create_SN_inst( pp["NODE"], pp["FRAME"] + 1,
                                  True, [[0, "X"], [1, False]],
                                  ulcch = "Hello there")
    else:
        inst = up.create_SN_inst( pp["NODE"], pp["FRAME"] + 1,
                                  False, [], ulcch = "Hello there")

    up.send(inst)
```

Dummy access policy

```
up = upper()
```

```
while True:
```

ZMQ message passing

```
    pp = up.extract(up.recv())
```

```
    print("SN : %s, Frame : %s" % (pp["NODE"], pp["FRAME"]))
```

```
    if pp["DLCCH"] == "GR_Con_22":
```

```
        inst = up.create_SN_inst( pp["NODE"], pp["FRAME"] + 1,  
                                  True, [[0, "X"], [1, False]],  
                                  ulcch = "Hello there")
```

```
    else:
```

```
        inst = up.create_SN_inst( pp["NODE"], pp["FRAME"] + 1,  
                                  False, [], ulcch = "Hello there")
```

```
up.send(inst)
```

Dummy access policy

```
up = upper()
```

```
while True:
```

ZMQ message passing

```
    pp = up.extract(up.recv())
```

```
    print("SN : %s, Frame : %s" % (pp["NODE"], pp["FRAME"]))
```

```
    if pp["DLCCH"] == "GR_Con_22":
```

```
        inst = up.create_SN_inst(
            pp["NODE"], pp["FRAME"] + 1,
            True, [[0, "X"], [1, False]],
            ulcch = "Hello there")
```

```
    else: PMT dict
```

```
        inst = up.create_SN_inst(
            pp["NODE"], pp["FRAME"] + 1,
            False, [], ulcch = "Hello there")
```

```
    up.send(inst)
```

Modular physical layer

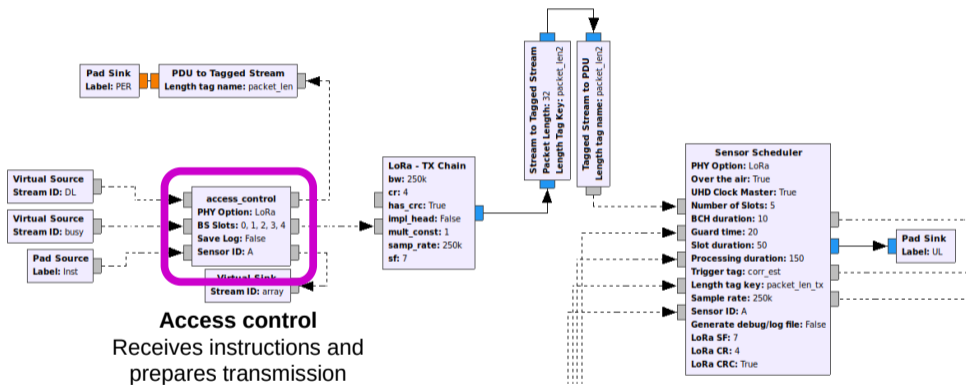


Figure: Sensor architecture

Modular physical layer

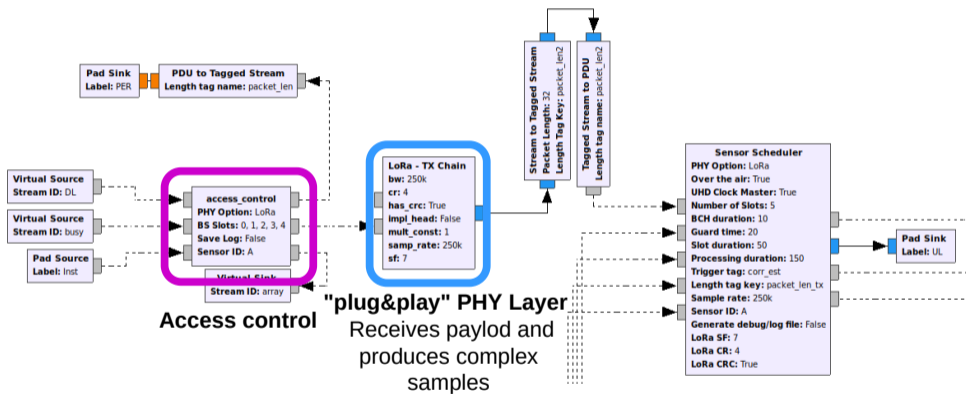


Figure: Sensor architecture

Modular physical layer

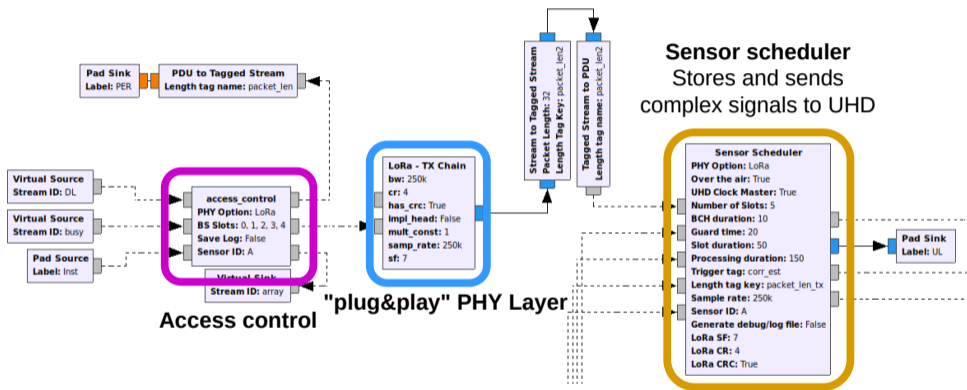
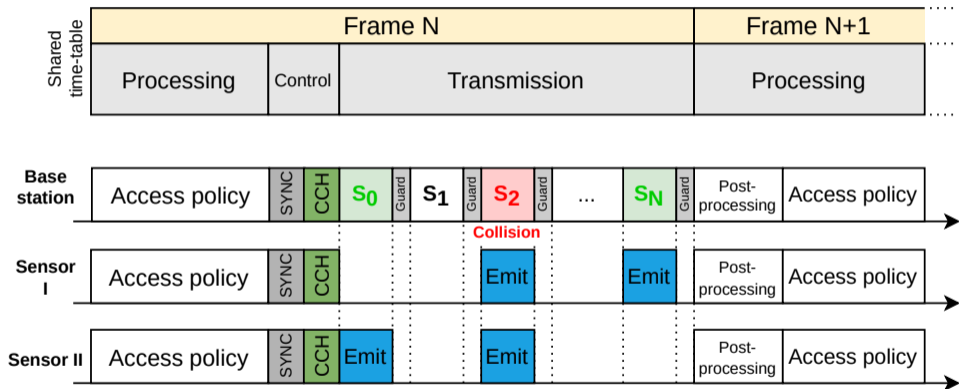
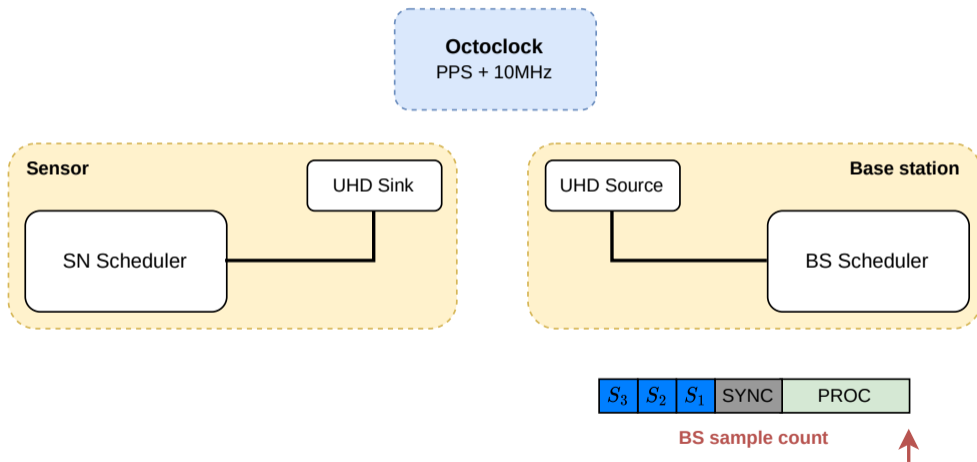


Figure: Sensor architecture

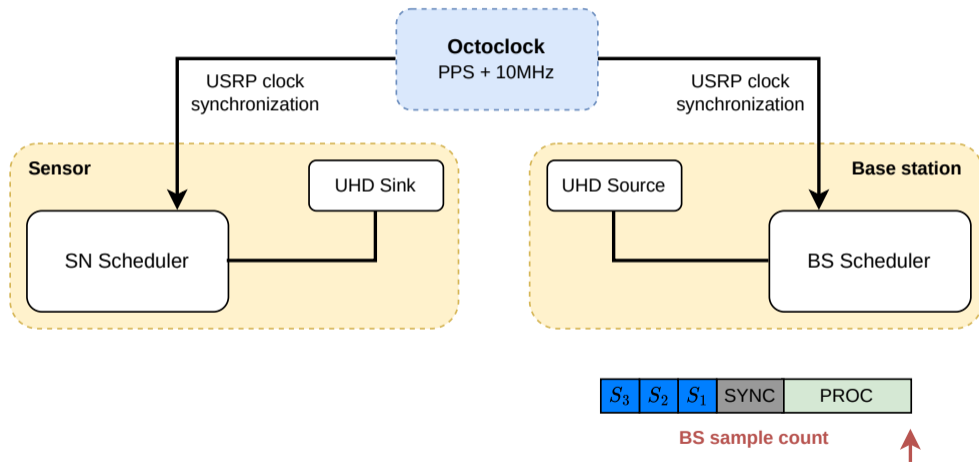
Synchronization



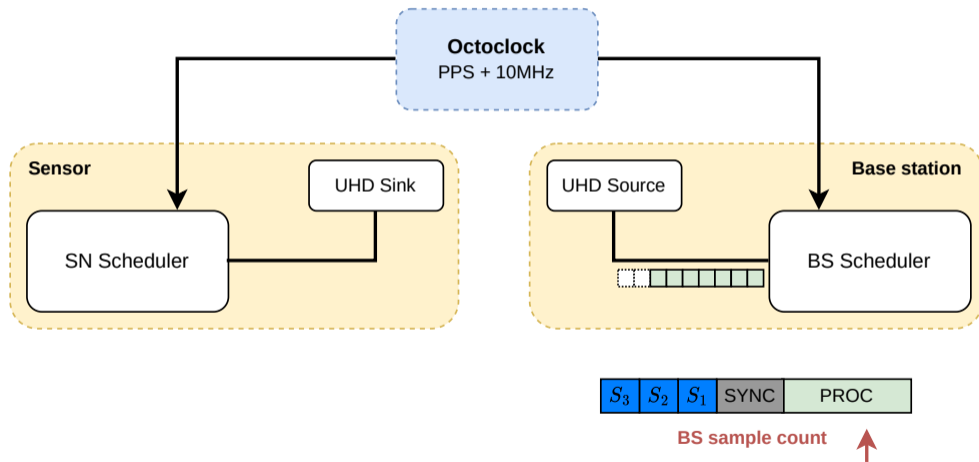
Synchronization



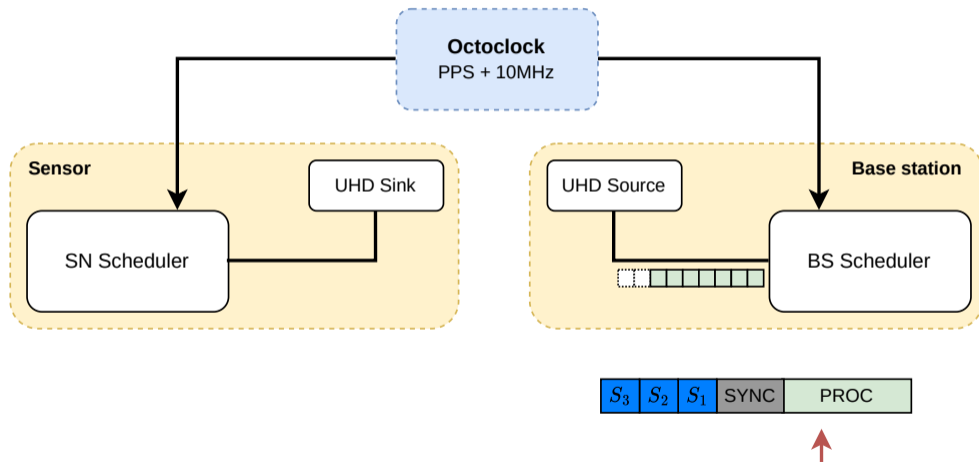
Synchronization



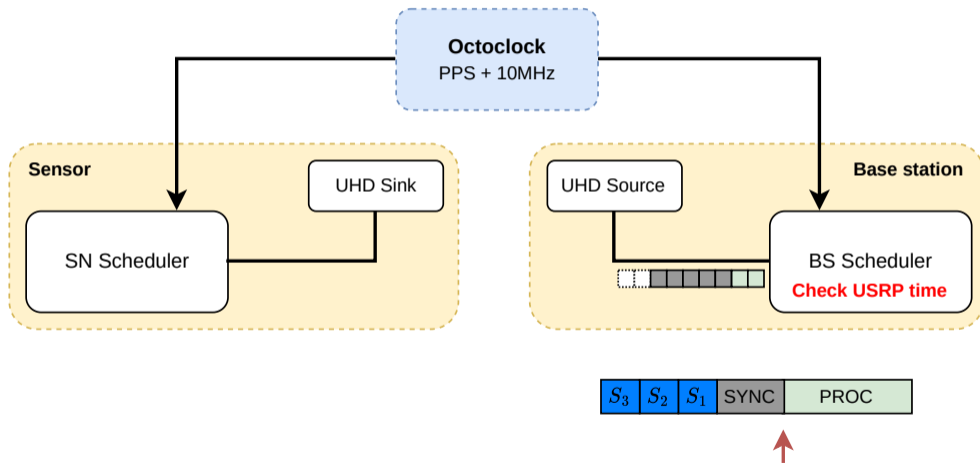
Synchronization



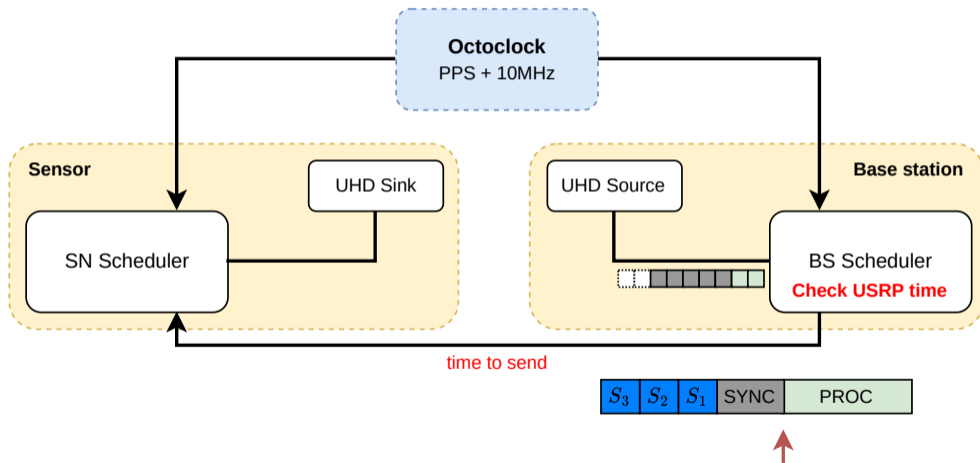
Synchronization



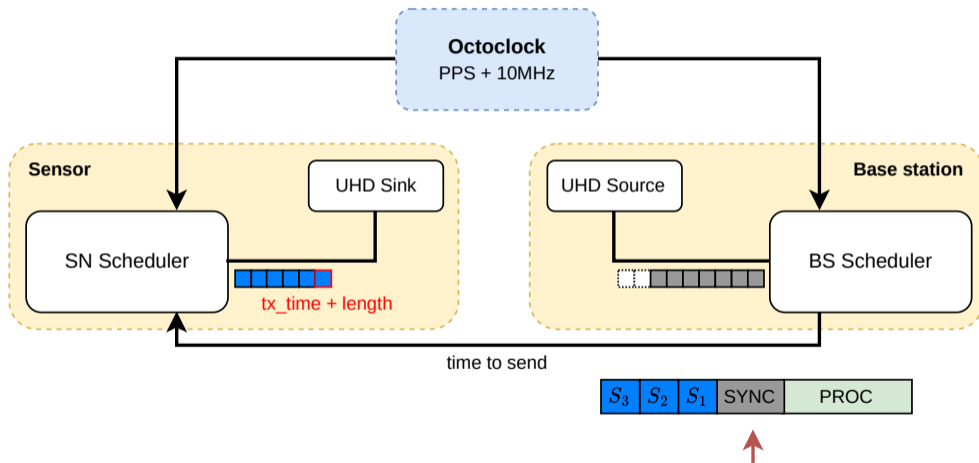
Synchronization



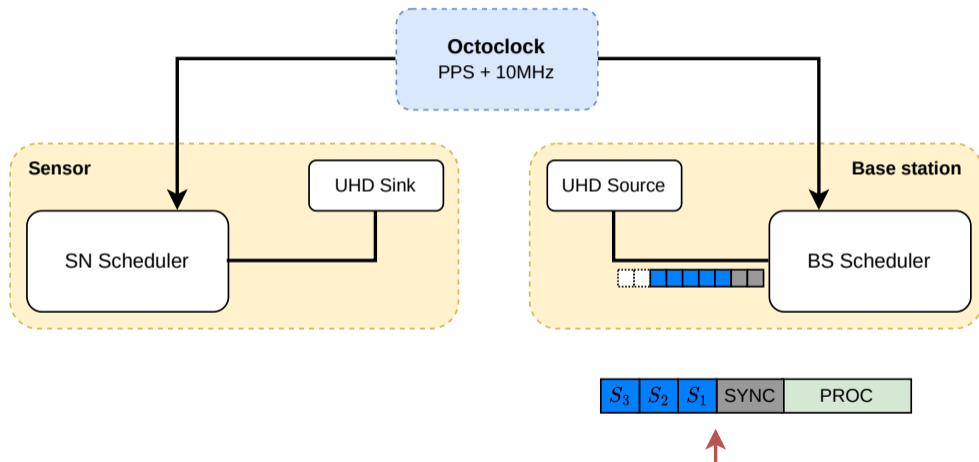
Synchronization



Synchronization



Synchronization



Synchronization

TX synchronization

- **0 ± 150ns** delay for two nodes transmitting at the same time¹

¹Measurement made @10MHz samp_rate within FIT/CorteXlab by Cyrille Morin, Centrale Supélec, France  

Synchronization

TX synchronization

- $0 \pm 150\text{ns}$ delay for two nodes transmitting at the same time¹

RX synchronization

- avg **0.7ms** delay between one node transmission and RX window

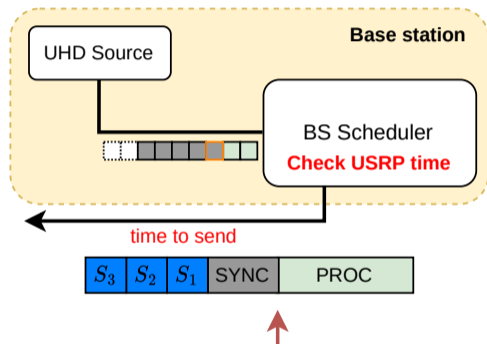


Figure: RX Synchronization

¹Measurement made @10MHz samp_rate within FIT/CorteXlab by Cyrille Morin, Centrale Supélec, France

Synchronization

TX synchronization

- **$0 \pm 150\text{ns}$** delay for two nodes transmitting at the same time¹

RX synchronization

- **avg 0.7ms** delay between one node transmission and RX window

Corrected RX synchronization

- **Expecting $1.1\mu\text{s}$** delay¹

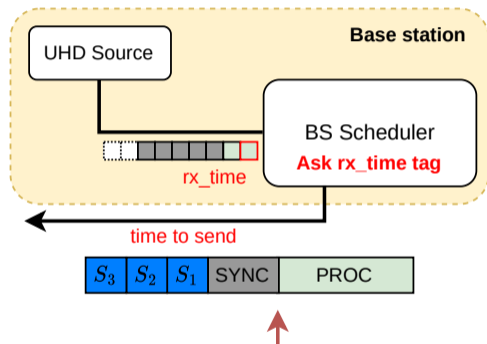


Figure: RX Synchronization

¹Measurement made @10MHz samp_rate within FIT/CorteXlab by Cyrille Morin, Centrale Supélec, France

Synchronization

TX synchronization

- **$0 \pm 150\text{ns}$** delay for two nodes transmitting at the same time¹

RX synchronization

- **avg 0.7ms** delay between one node transmission and RX window

Corrected RX synchronization

- **Expecting $1.1\mu\text{s}$** delay¹

Generation of dataset

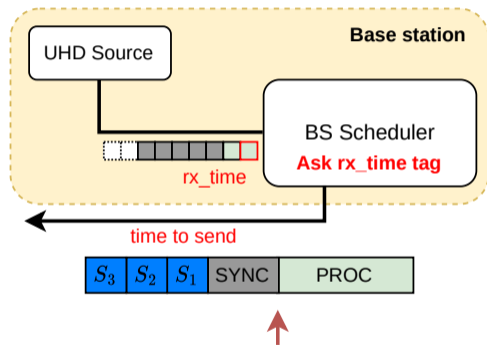


Figure: RX Synchronization

¹Measurement made @10MHz samp_rate within FIT/CorteXlab by Cyrille Morin, Centrale Supélec, France

Usage

Running the framework on your own local computer :

- Development phase;
- Theoretical results.



Usage

Running the framework on your own local computer :

- Development phase;
- Theoretical results.

Available PHY layer

- LoRa ²
- Nb IoT, under development
- Yours ...



²"An Open-Source LoRa Physical Layer Prototype on GNU Radio", J. Tapparel et al, EPFL

Usage

Running the framework on your own local computer :

- Development phase;
- Theoretical results.

Available PHY layer

- LoRa ²
- Nb IoT, under development
- Yours ...



Possibility to emulate nodes

²"An Open-Source LoRa Physical Layer Prototype on GNU Radio", J. Tapparel et al, EPFL

Tutorial

Available on the FIT/CorteXlab wiki [under development]:

- Two nodes
- Random access policies

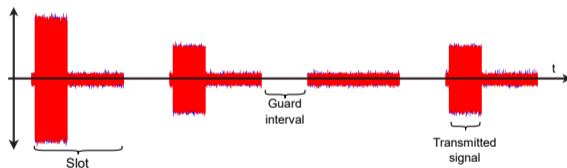


Figure: Received signal at the BS

S3-CAP tutorial : https://wiki.cortexlab.fr/doku.php?id=ephy1_framework_v2

S3_CAP Framework

Current and future work :

- **Nb IoT** : Finalisation of the Nb IoT PHY layer
- **RL access policies** : Apply a RL access policies method designed for LoRa system
- **Interference statistics** : Study the distribution of baseband IQ samples during collision

Thanks !

If you have any additional questions or requests, please contact us at :

amaury.paris@insa-lyon.fr

leonardo.cardoso@insa-lyon.fr

- **FIT/CortexXlab** : <http://www.cortexlab.fr/>
- **Wiki FIT/CorteXlab** : <https://wiki.cortexlab.fr/doku.php>
- **S3-CAP tutorial** :
https://wiki.cortexlab.fr/doku.php?id=ephy1_framework_v2