

# Kuiper Linux Distribution - simplify hardware prototyping with GNU Radio

Michael Hennerich

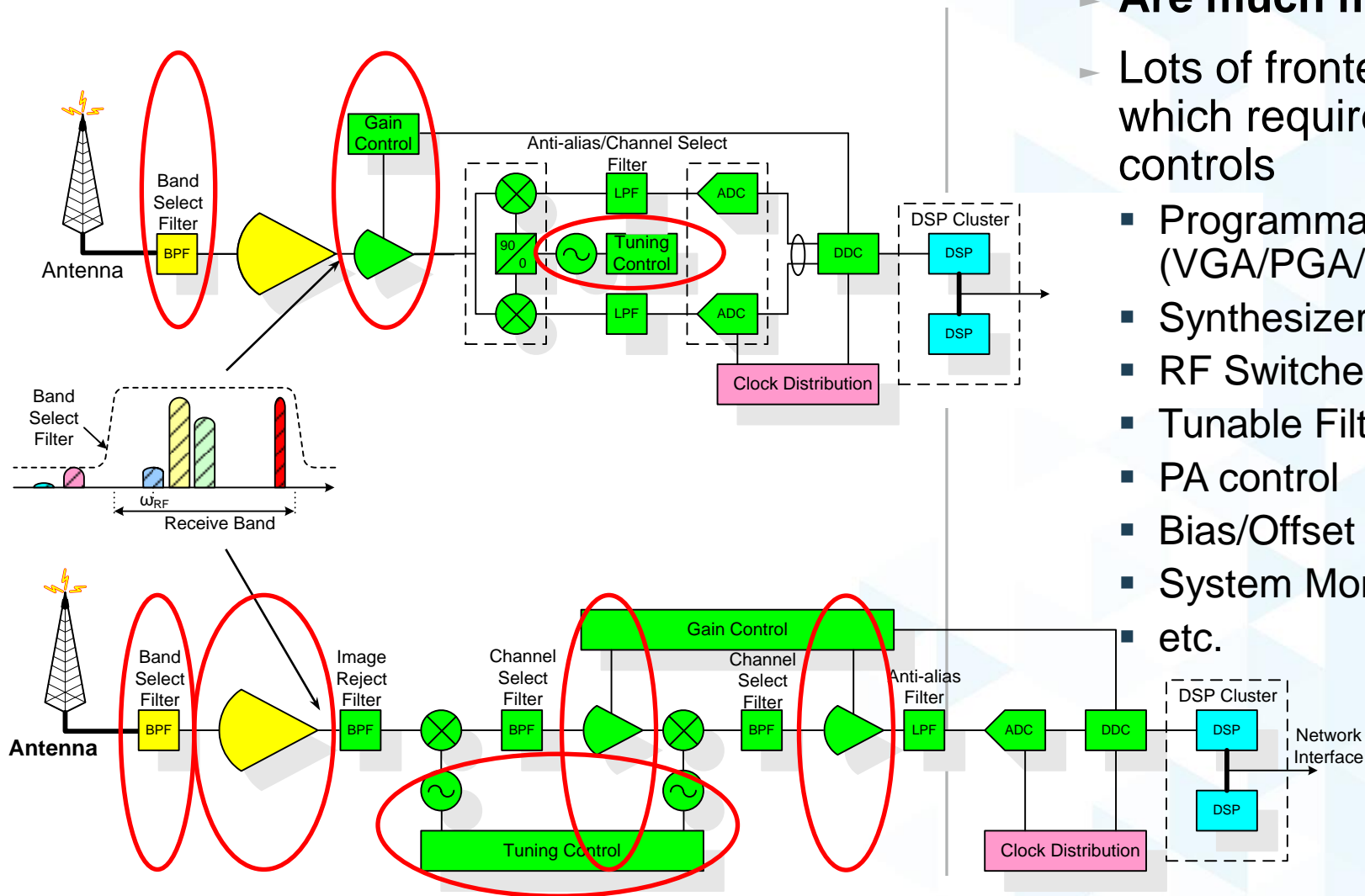
Jon Kraft



AHEAD OF WHAT'S POSSIBLE™

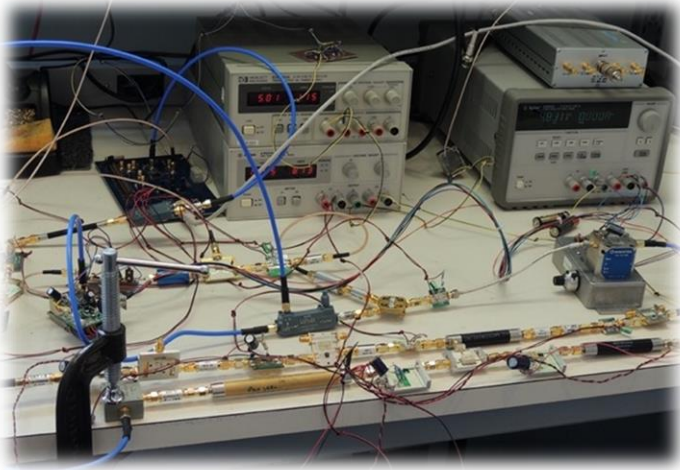


# (Software Defined) Radio Systems

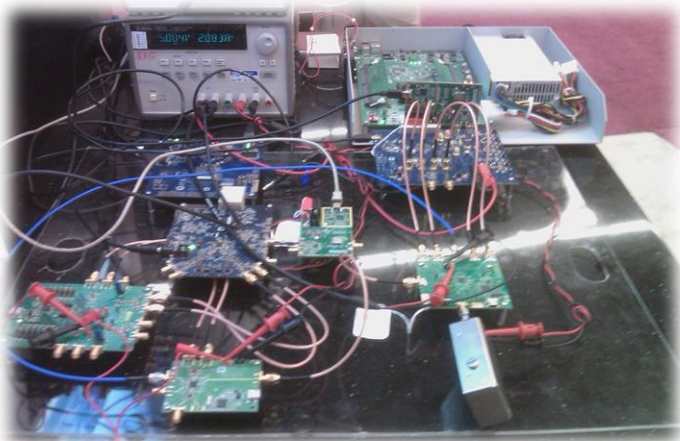


- ▶ Are much more than Digitizers!
- ▶ Lots of frontend **active** RF components which require configuration and runtime controls
  - Programmable Amplifiers and Attenuators (VGA/PGA/DSA)
  - Synthesizers, PLLs, UP/DN Converters
  - RF Switches (TRX, Filters)
  - Tunable Filters, Beamformers
  - PA control
  - Bias/Offset control
  - System Monitoring (V, I, T)
  - etc.

# Typical prototyping challenges



Typical Lab Bench

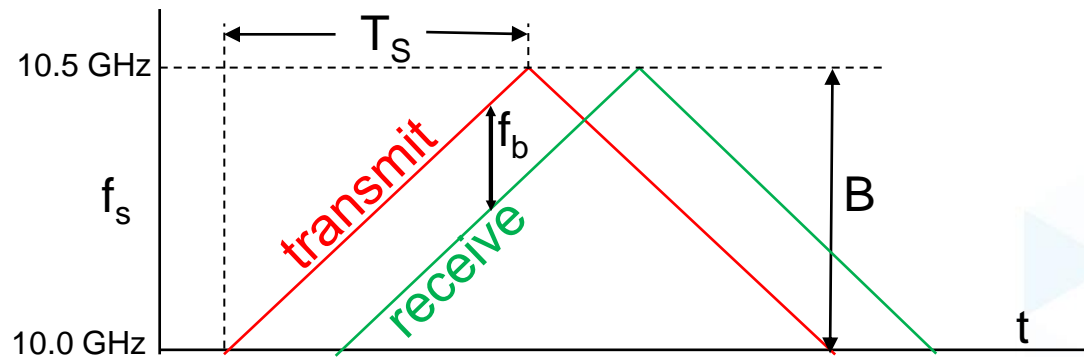


- ▶ Observation
  - Lots of interconnected evaluation/prototype circuit boards
  - Lots of different supply voltages needed
  - No homogeneous way to control this mess
- ▶ Implication
  - Loss of RF performance
  - Mechanically difficult to test this in the field
  - Control nightmare
    - Every active component has its own Windows EVAL software
    - Sometimes missing software and drivers
    - No way to remote control
    - No easy way to integrate command and control into a GRC flowgraph
- ▶ Possible Solutions
  - Custom PCB design & System controller + Firmware
    - High cost and risk, typically comes 2nd after prototyping phase
  - Modular RF and Microwave building blocks
  - **Commercially of the shelf control hardware and FOSS software**
  - Industry standard soft- and hardware components
  - Single and powerful Embedded Controller which can control all components at a very high level

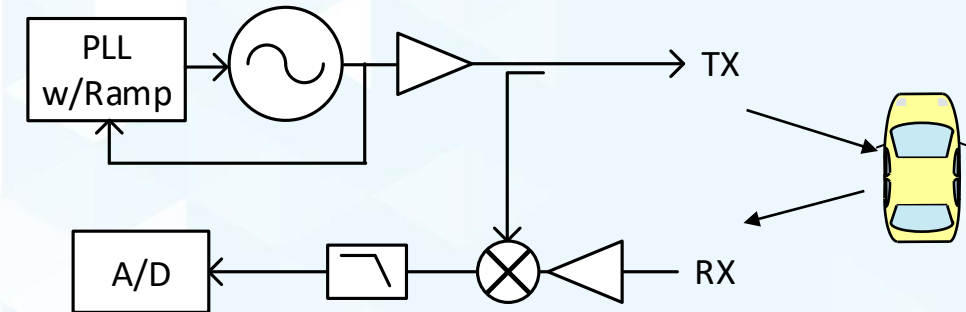
# Prototyping a FMCW Radar (in less than a day)

# FMCW Radar

- ▶ **FMCW:** Frequency Modulated Continuous Wave
- ▶ Different than Pulsed Radars
- ▶ **Beat frequency** proportional to time delay -> FFT for range estimation



## Basic Architecture



$$R = \frac{cT_s}{2B} (f_b)$$

*R* = distance to target

*c* = speed of light (3E8 m/s)

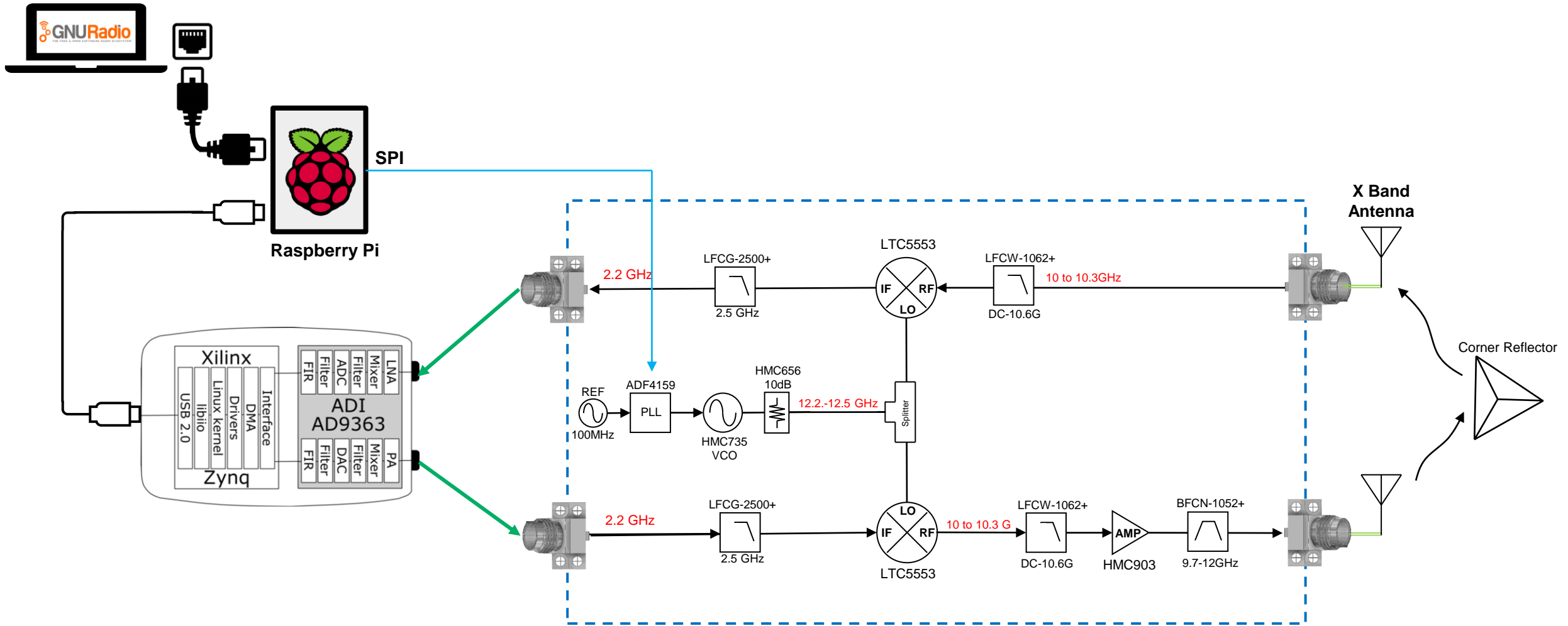
*T<sub>s</sub>* = transmit frequency ramp rate

*B* = bandwidth of the frequency ramp

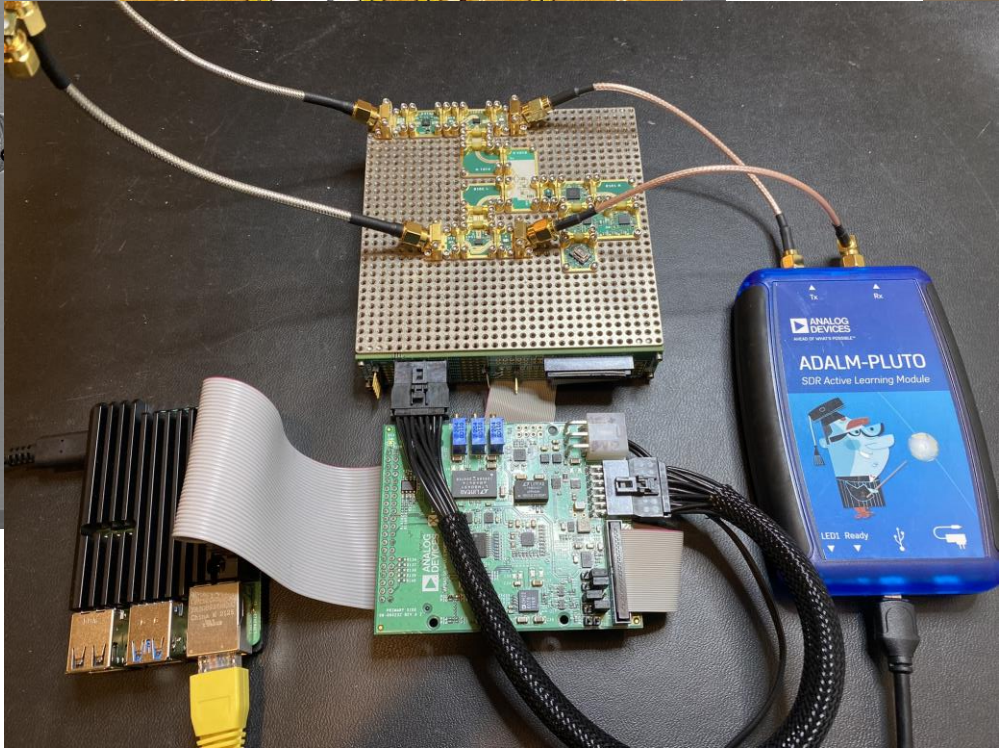
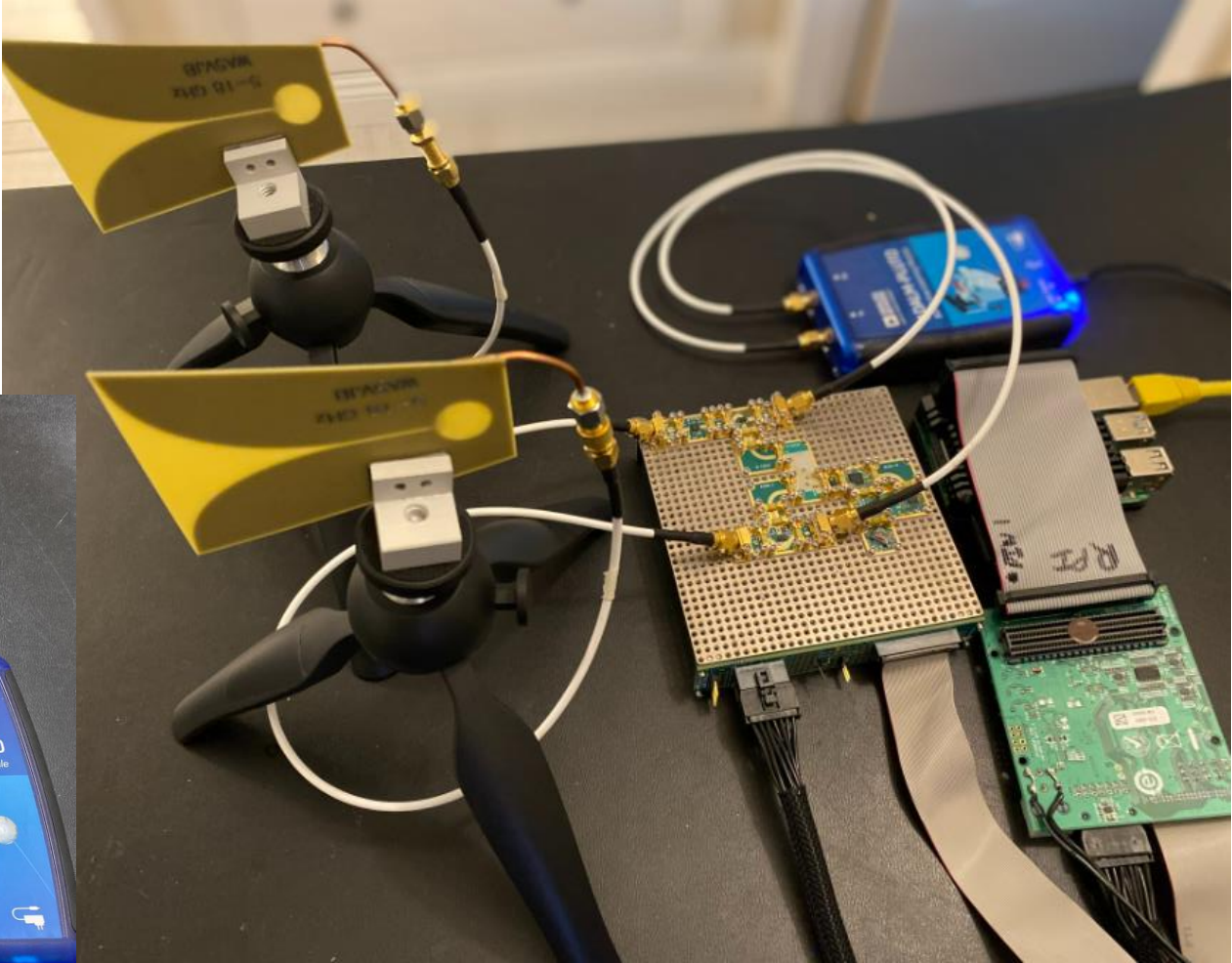
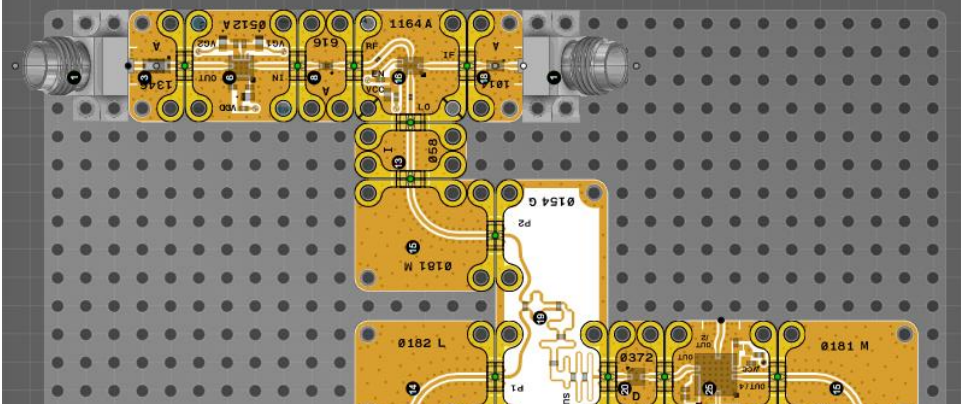
*f<sub>b</sub>* = transmit to receive frequency difference



# Build your own 10 GHz FMCW radar



# Build your own 10 GHz FMCW radar



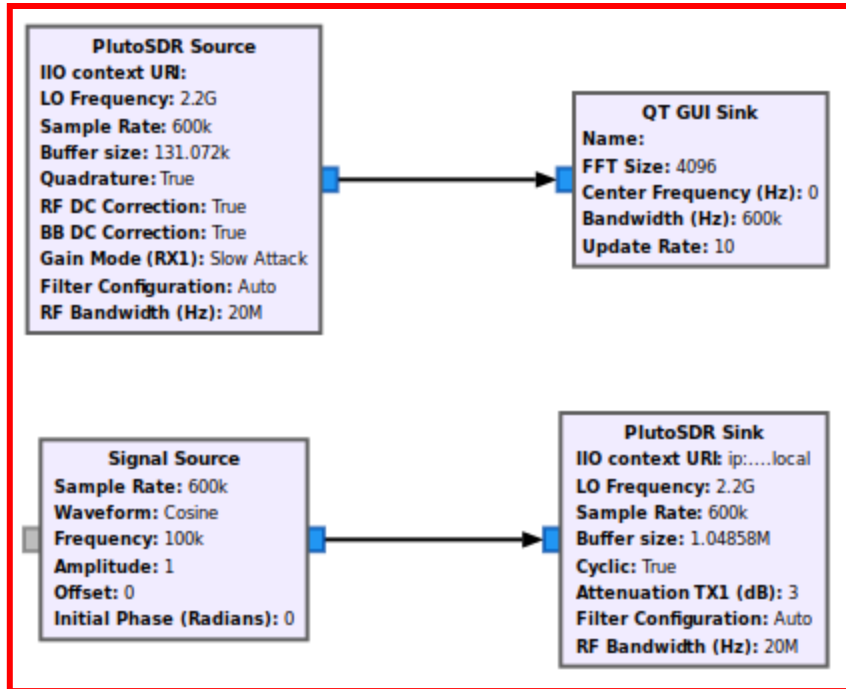
# Hello World FMCW!

**Options**  
Title: RAD-Pluto-ADF4159  
Output Language: Python  
Generate Options: QT GUI

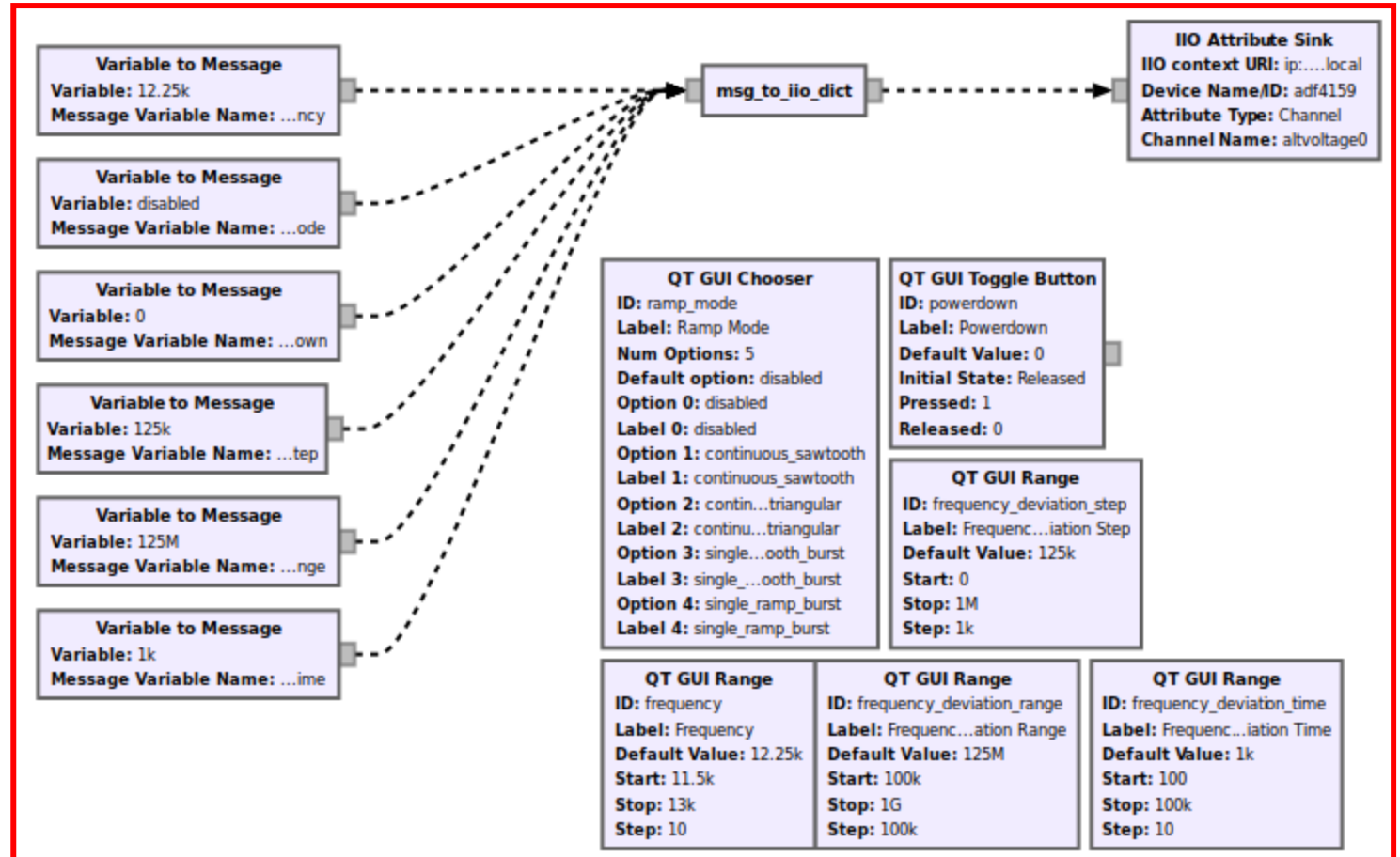
**Variable**  
ID: samp\_rate  
Value: 600k

**Variable**  
ID: fft\_size  
Value: 1.024k

**QT GUI Range**  
ID: LO  
Label: LO Frequency  
Default Value: 2.2G  
Start: 2.2G  
Stop: 2.5G  
Step: 1k



Digitizer Control (Pluto, USRP, etc.)



RF/MW Frontend Control



# Demo Time



# Example #1: RPi as control Bridge

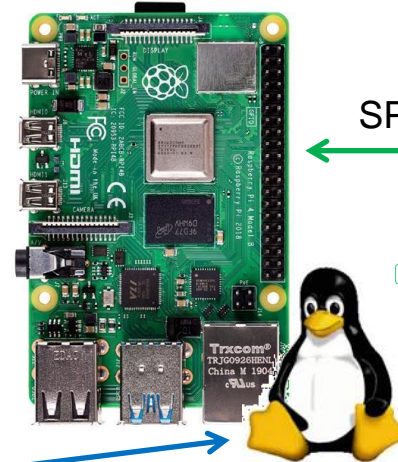
Your PC with: GRC, libiio  
Network connection to remote HW



Any network connection

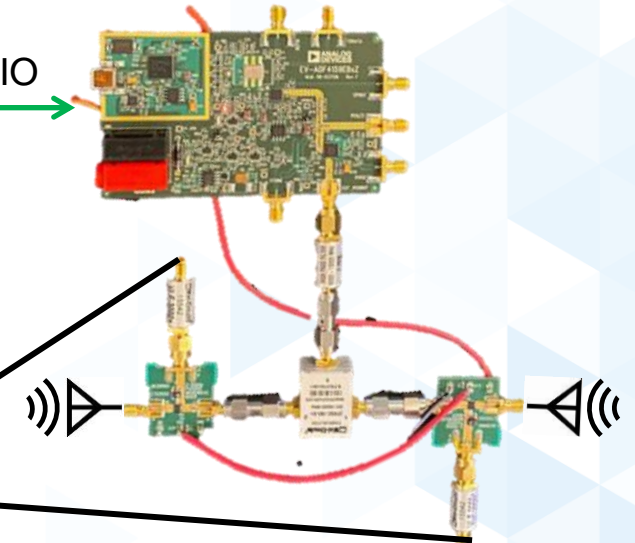
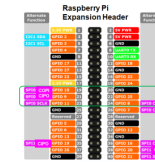
- Direct Ethernet cable
- USB-Ethernet
- Wireless

RPi, device drivers, IIO Daemon (Server)



SPI/I2C/GPIO

Controlled RF HW



- USB connection
- Virtual network
  - Direct USB
  - Serial
  - Mass Storage
  - OTG

RF Digitizer/Transceiver

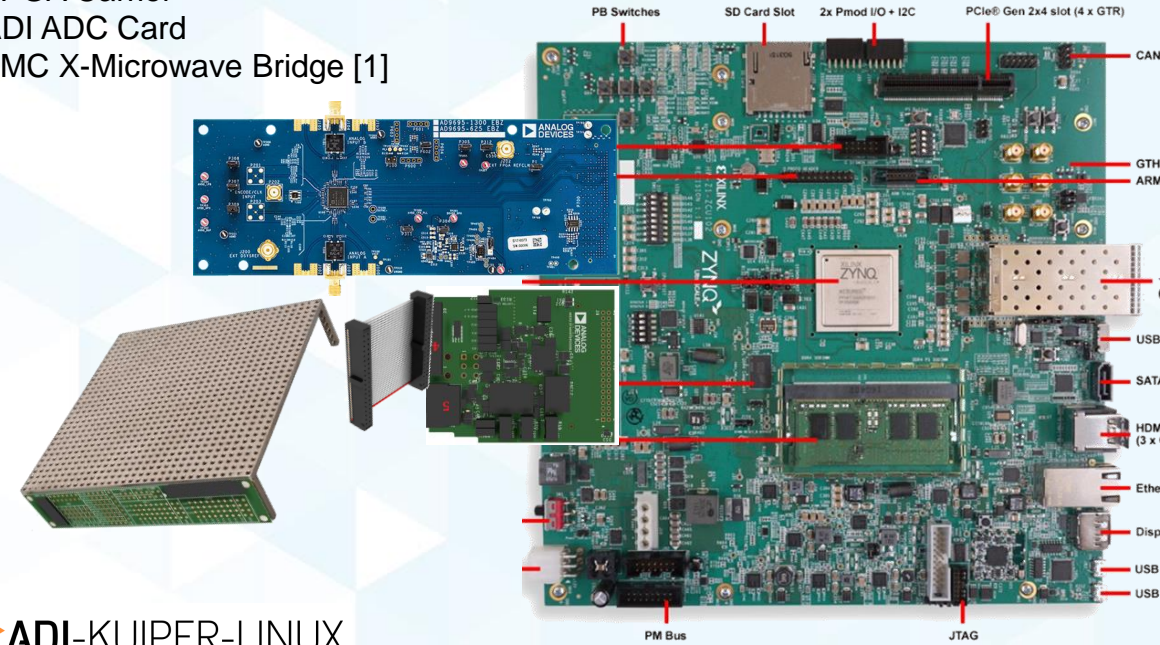




# Example #3: All digital back to the same SoC/FPGA

- ▶ All digital back to the same SoC
  - TRX data
  - TRX control
  - Clock control
  - Microwave/RF Control
- ▶ Enables:
  - Single / Cohesive environment to interface with digitizers and RF/Microwave
  - System level verification
  - Easier Power Supplies
  - Synchronization between digitizer and MW
  - Sync between data and control
  - Easier device driver verification and development
  - Control MW from GnuRadio, MATLAB or Python
  - Simplifies path to production (all SW together, all HW together)

- ▶ FPGA Carrier
- ▶ ADI ADC Card
- ▶ FMC X-Microwave Bridge [1]



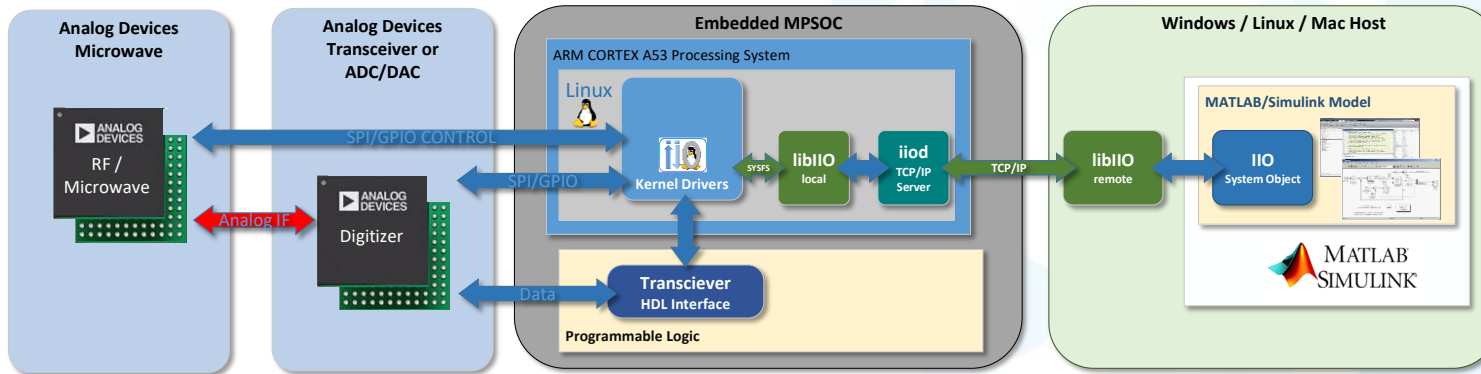
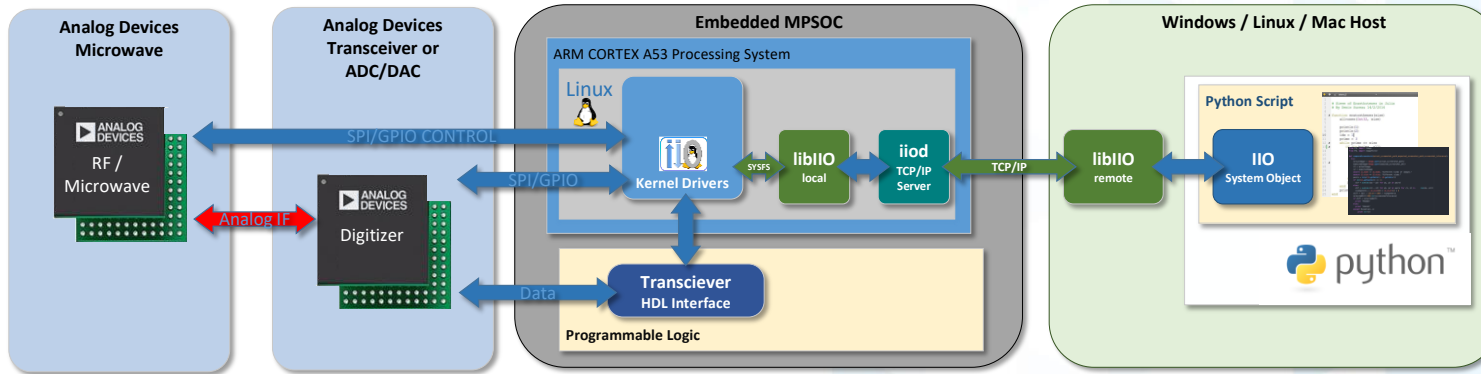
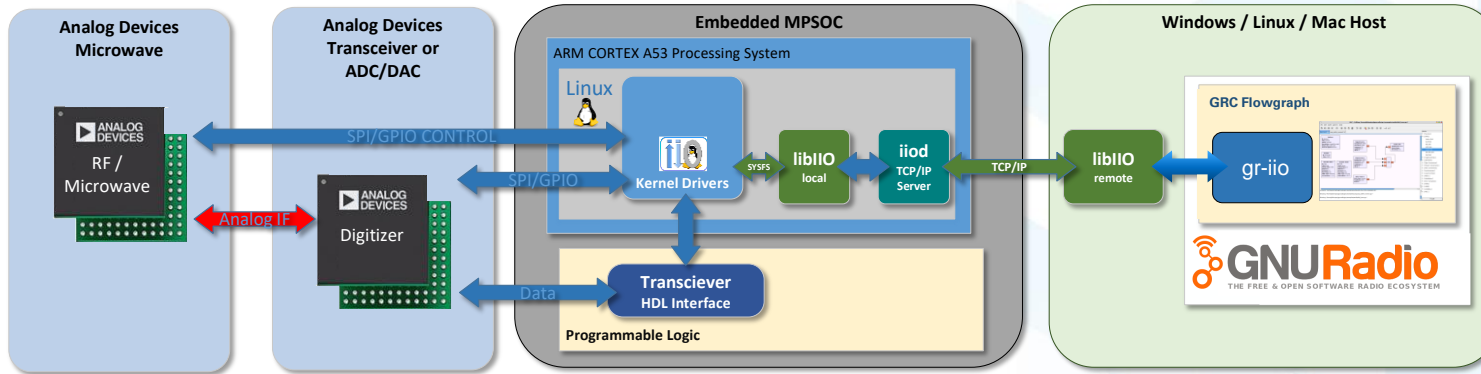
 **ADI-KUIPER-LINUX**  
LINUX DEVICE DRIVERS FOR ADI PERIPHERALS

- ▶ ADI RF SOM
- ▶ ADI Carrier
- ▶ FMC X-Microwave Bridge [1]





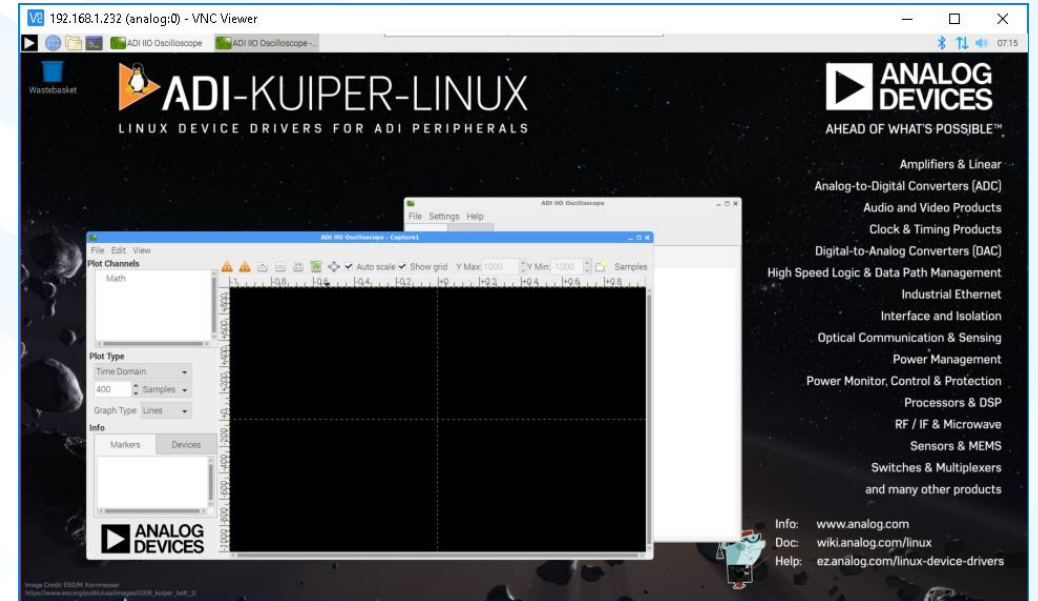
# Single cohesive software solution



# ADI-KUIPER-LINUX

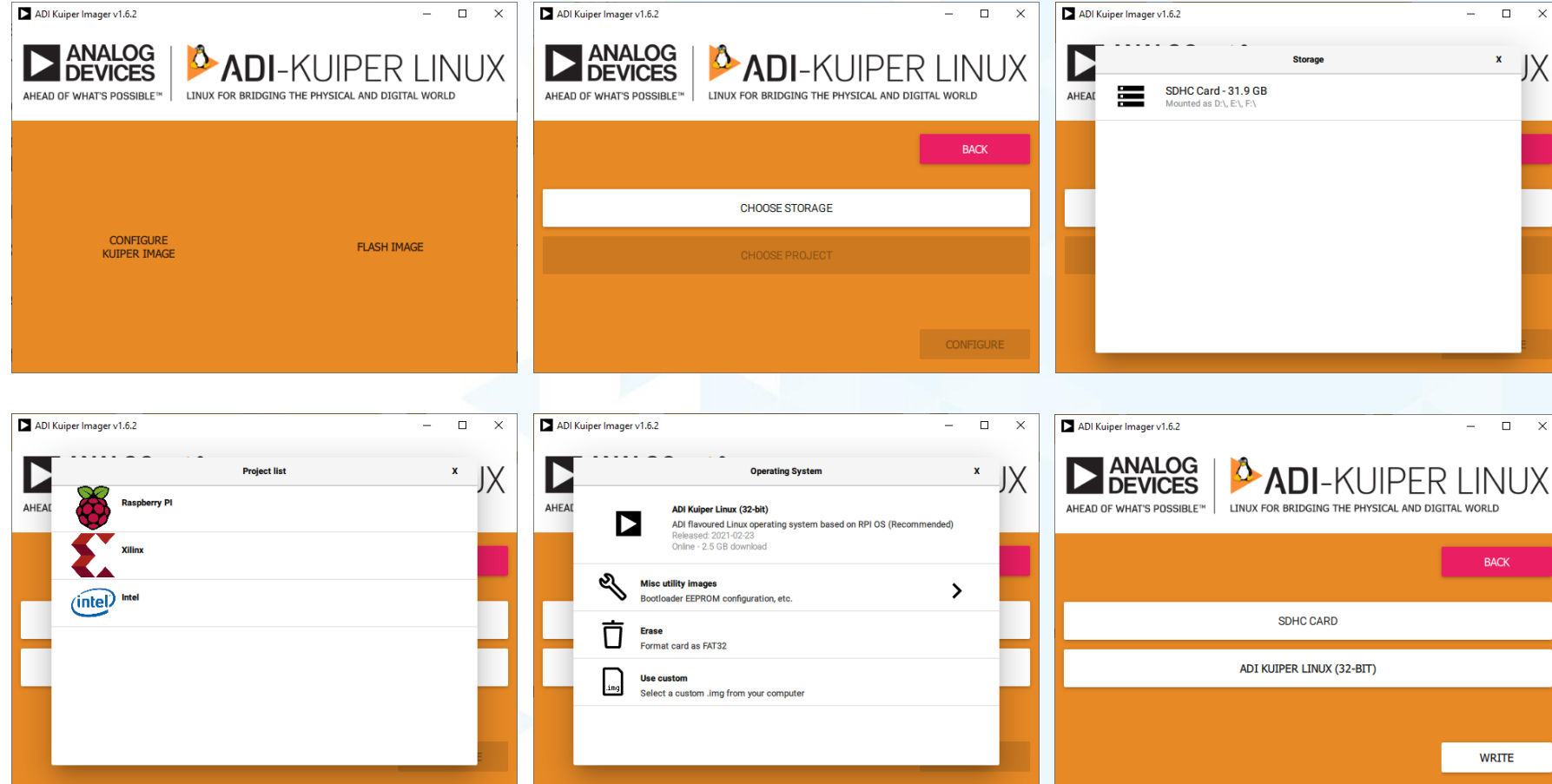
LINUX DEVICE DRIVERS FOR ADI PERIPHERALS

- ▶ A distribution based on Raspbian but NOT only for Raspberry Pi [2].
  - It incorporates **Linux device drivers for ADI products [6]** and is created with **ease of use** in mind.
  - Supports multiple ADI Circuit Note and Eval boards with FMC, RPi HEAD, Arduino and PMOD connectors.
- ▶ **Minimize the barriers** to integrating hardware devices into a Linux-based system.
- ▶ ADI Kuiper Linux solves this problem, and includes a host of additional applications, software libraries, and utilities.



# Kuiper Imager Utility [4]

- ▶ Windows/Linux/Mac
- ▶ Downloads Image file from the internet
- ▶ Writes image to removable media storage device
- ▶ Eases customization for a specific Base Platform + Add-On or Attach
- ▶ Released in the coming weeks



Alternative: `$wget https://swdownloads.analog.com/cse/kuiper/image_2022-08-04-ADI-Kuiper-full.zip`

`$unzip image_2022-08-04-ADI-Kuiper-full.zip`

`$sudo dd if=2022-08-04-ADI-Kuiper-full.img of=/dev/sdX bs=4M`

# Customizing?

- ▶ While Raspbian targets Raspberry Pi platform boards, ADI Kuiper Linux supports several other platforms in addition
  - Arduino form factor ARM based FPGA platforms such as
    - Intel/TerASIC DE10-Nano
    - Xilinx/Digilent Cora Z7
  - Most popular FMC FPGA carriers from Xilinx/AMD and Intel with ARM/ARM64 support
    - Zynq7000 (Zed board, ZC706, ZC702)
    - MPSoC (ZCU102)
    - SoC FPGA (A10Soc, A5Soc)
- ▶ Configure the Kuiper SD card to be used with a specific Hardware
  - Base Platform + Add-On or Attach
  - Move boot files from folders to the root of the FAT partition so that they can be picked up by the first stage bootloader (Intel or Xilinx/AMD FPGAs)
    - FPGA Bitstreams
    - Linux kernel blobs
    - Devicetree blobs
  - Instruct early-stage bootloader to load a certain overlay (Rpi: Edit config.txt)



# Devicetree (overlay)

- ▶ Tree data structure with nodes that describe the physical devices in a system.
  - ▶ Describes device information in a system that cannot be dynamically detected.
  - ▶ Organized in nodes and properties
  - ▶ Overlays enables addition of extra nodes to the live device tree of an embedded Linux system.
  - ▶ **dts, dtsti**: devicetree source
    - Human-readable
    - Textual
    - Used when editing devicetree files
  - ▶ **dtb, dtbo**: devicetree blob
    - Machine-readable
    - Binary
    - Flattened
    - The Device tree compiler (dtc) generates dtb, dtbo
- \$dtc -I dts -O dtb rpi-adf4159-overlay.dts > rpi-adf4159.dtbo**

## Example file: rpi-adf4159-overlay.dts [3][5]

```
/dts-v1/;  
/plugin/;
```

### Parent Node – SPI BUS #0

```
&spi0 {
```

```
#address-cells = <1>;  
#size-cells = <0>;  
status = "okay";
```

### New device node

```
adf4159:adf4159@0 {
```

```
compatible = "adi,adf4159";
```

### Driver to bind

```
reg = <0x0>;
```

### SPI Chip Select 0

```
spi-max-frequency = <12500000>;
```

```
/* Clocks */
```

```
clocks = <&clkkin>;
```

```
clock-names = "clkkin";
```

```
clock-output-names = "rf_out";
```

```
#clock-cells = <0>;
```

```
adi,power-up-frequency-hz = /bits/ 64 <6000000000>;
```

```
/* --- snip ---- */
```

```
};
```

```
};
```

- ▶ The Analog Devices kernel tree contains a number of such Device Tree Overlays in the *arch/arm/boot/dts/overlays* folder.
- ▶ Each of those overlays, stored in .dts file gets compiled into a .dtbo files using dtc.
- ▶ On the SD card those .dtbo files reside in *BOOT\overlays* or from within the rootfs at */boot/overlays*
- ▶ Those .dtbo can be loaded and applied to the main Device Tree by adding the following statement to the Rpi config.txt file:

## ▶ Load at boot:

- config.txt file is read by the early-stage boot firmware

## ▶ dtoverlay=overlay-name,overlay-arguments

EXAMPLE:

```
dtoverlay=rpi-adf4159
```

## ▶ Load from command line:

### ▶ dtoverlay <overlay> [<param>=<val>...]

EXAMPLE:

```
root@analog:~# dtoverlay rpi-adf4159
```

```
root@analog:~# dtoverlay -l
```

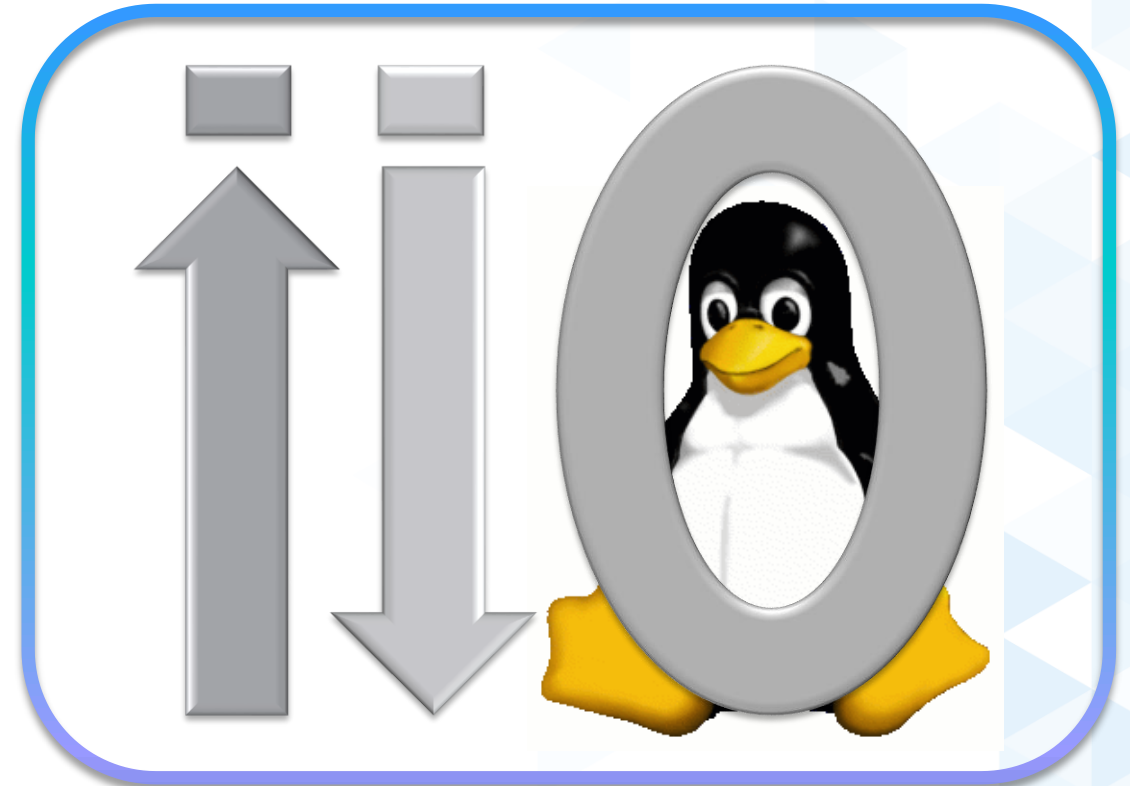
Overlays (in load order):

```
0: rpi-adf4159
```

```
root@analog:~# systemctl restart iiod
```

# What is IIO?

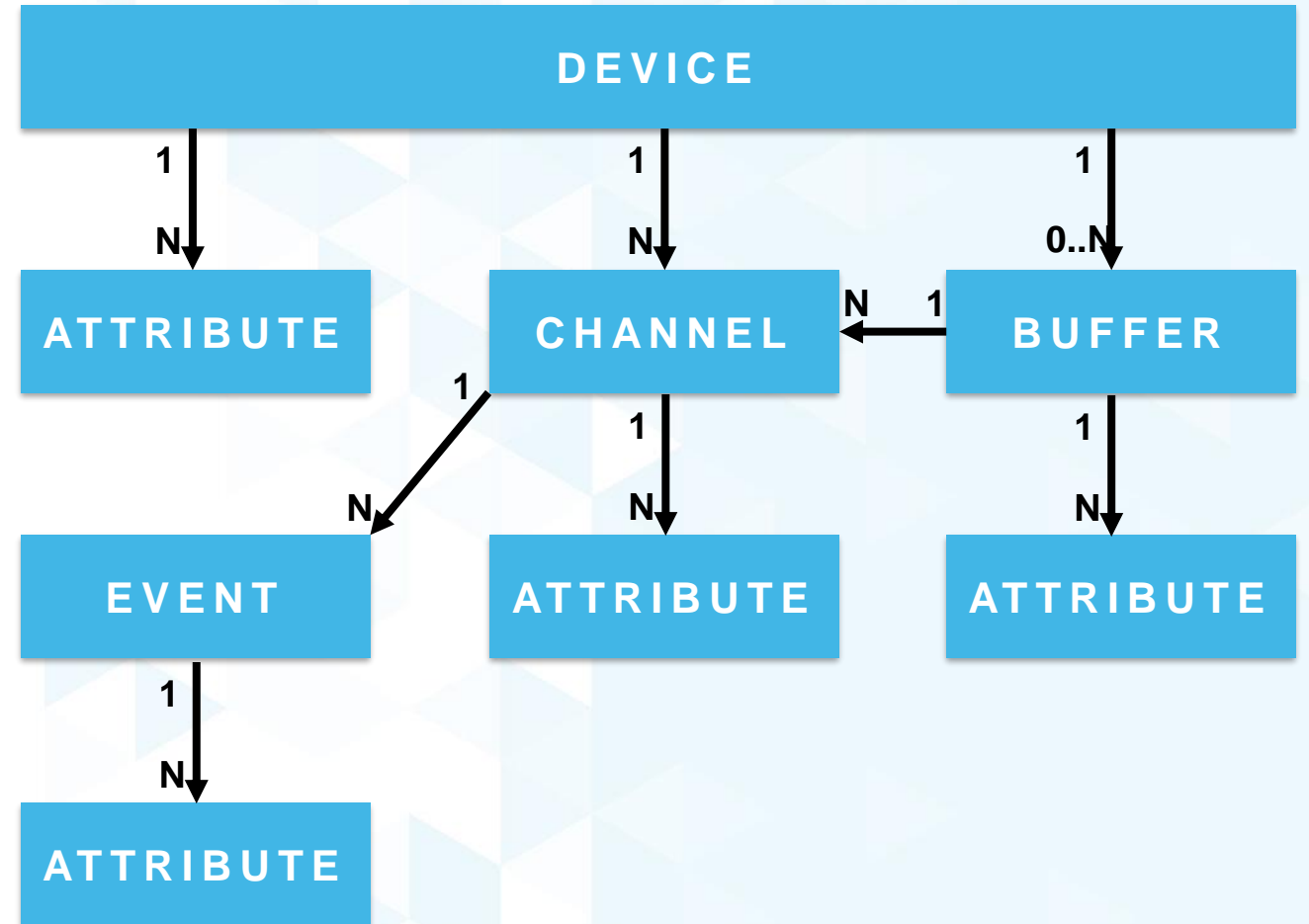
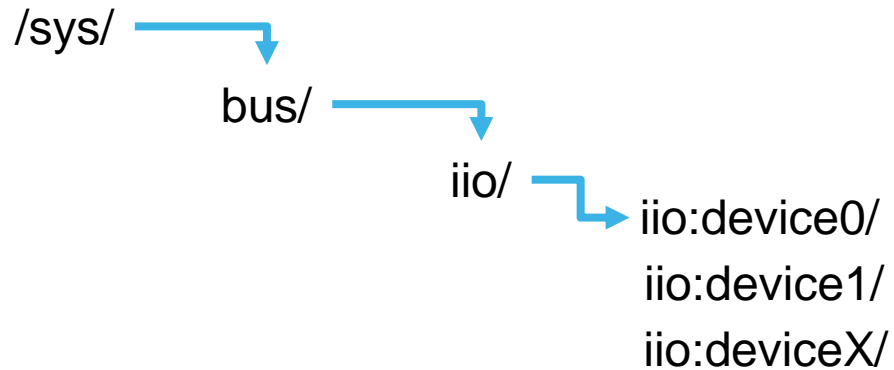
- ▶ Linux kernel **I**ndustrial **I**nterface / **O**utput framework
  - Not really just for Industrial IO
  - All non-HID IO
  - ADC, DAC, TRX, light, accelerometer, gyro, magnetometer, humidity, temperature, pressure, rotation, angular momentum, chemical, health, proximity, counters, amplifiers, synthesizers, RF Up/Down converters, tunable filters, etc.
- ▶ In the upstream Linux kernel for more than 10 years.
- ▶ Mailing list:
  - [linux-iio@vger.kernel.org](mailto:linux-iio@vger.kernel.org)



<https://www.kernel.org/doc/html/latest/driver-api/iio/index.html>

# IIO – Devices

- ▶ Main structure
- ▶ Typically corresponds to a single physical hardware device
- ▶ Represented as directories in sysfs





# IIO – Attributes

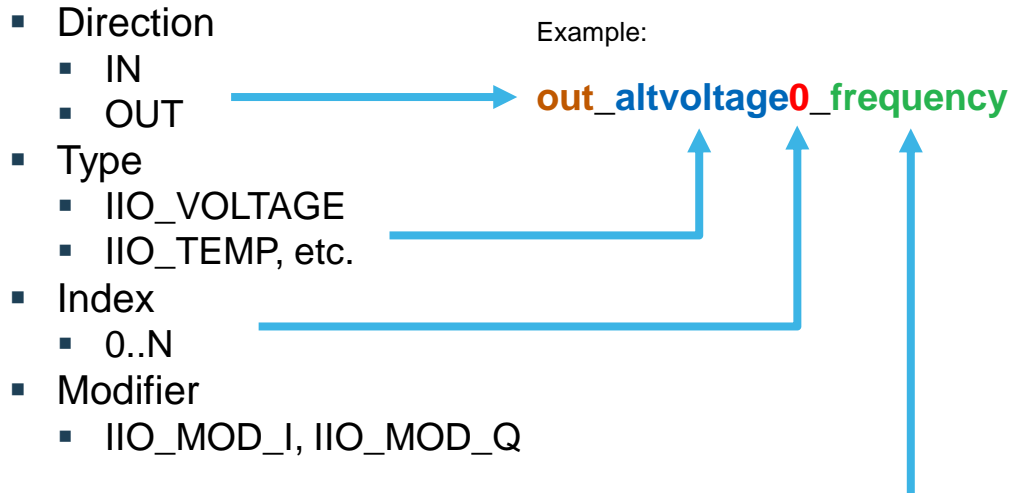
- ▶ Describe hardware capabilities
- ▶ Allow to configure hardware features
  - SAMPLING\_FREQUENCY
  - POWERDOWN
  - PLL\_LOCKED
  - SYNC\_DIVIDERS
  - etc.
- ▶ Represented as files in sysfs



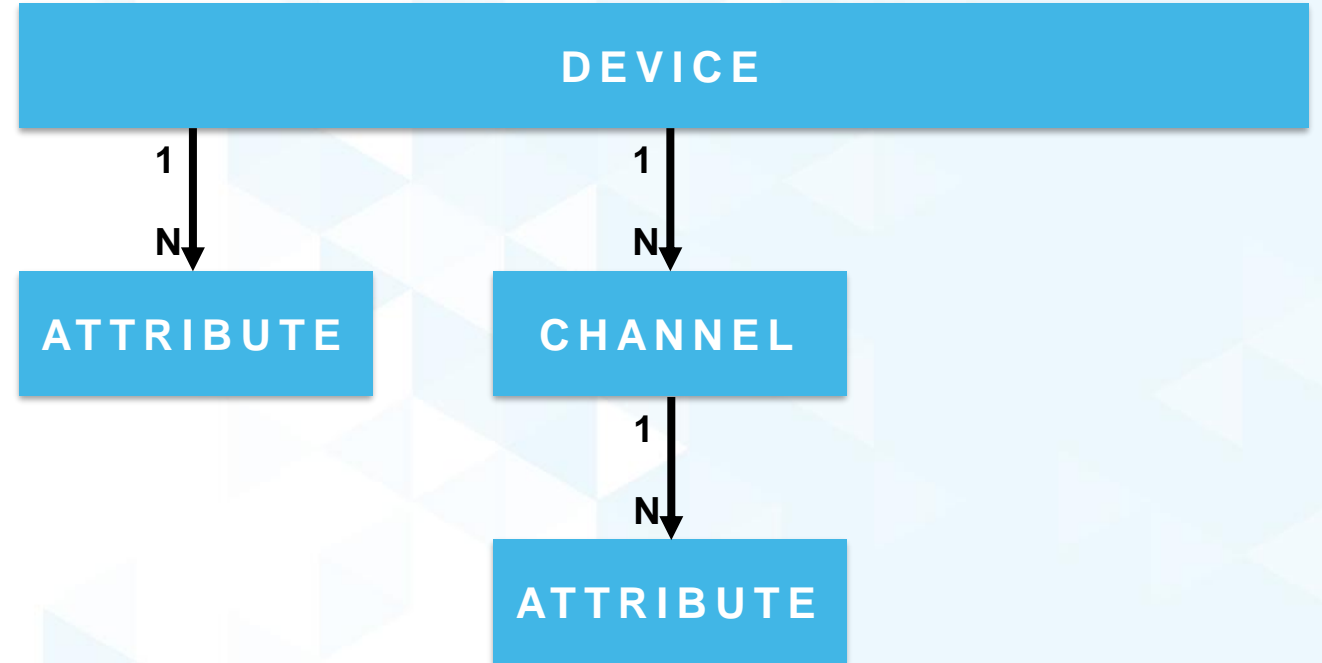
```
# ls /sys/bus/iio/devices/  
iio:device0 iio:device1 iio:device2 iio:device3 iio:device4  
# cat /sys/bus/iio/devices/*/name  
adm1177  
ad9361-phy  
xadc  
cf-ad9361-dds-core-lpc  
cf-ad9361-lpc  
#
```

# IIO – Channels

- ▶ Representation of a data channel
- ▶ Has direction, type, index and modifier



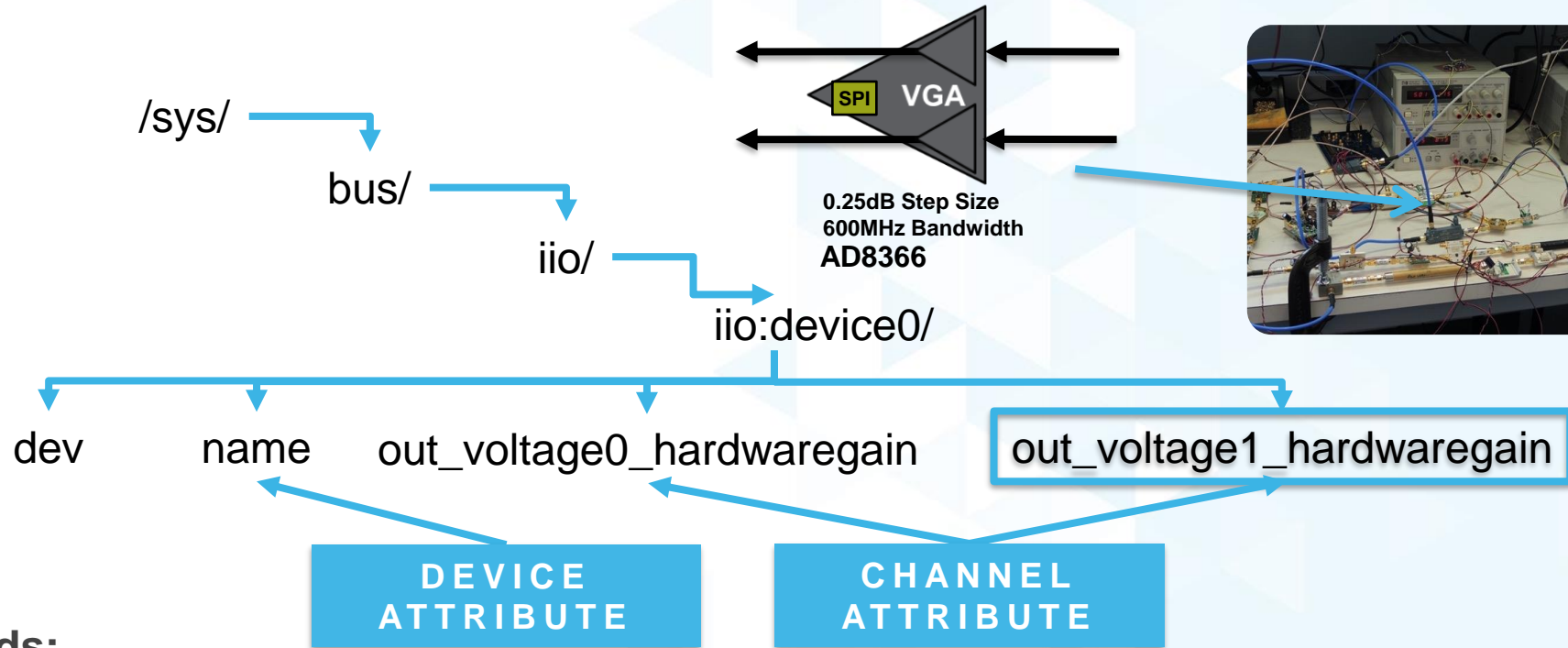
- ▶ Channel Attributes provide additional information
  - RAW
  - SCALE
  - OFFSET
  - FREQUENCY
  - PHASE
  - HARDWAREGAIN
  - etc.



- ▶ Example: Read voltage from ADC Channel X in mV

- ▶  $VoltageX\_mV = (in\_voltageX\_raw + in\_voltageX\_offset) * in\_voltageX\_scale$

# VGA/PGA Gain or DSA Attenuation Control

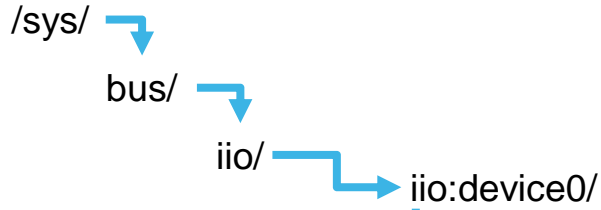


## Shell Commands:

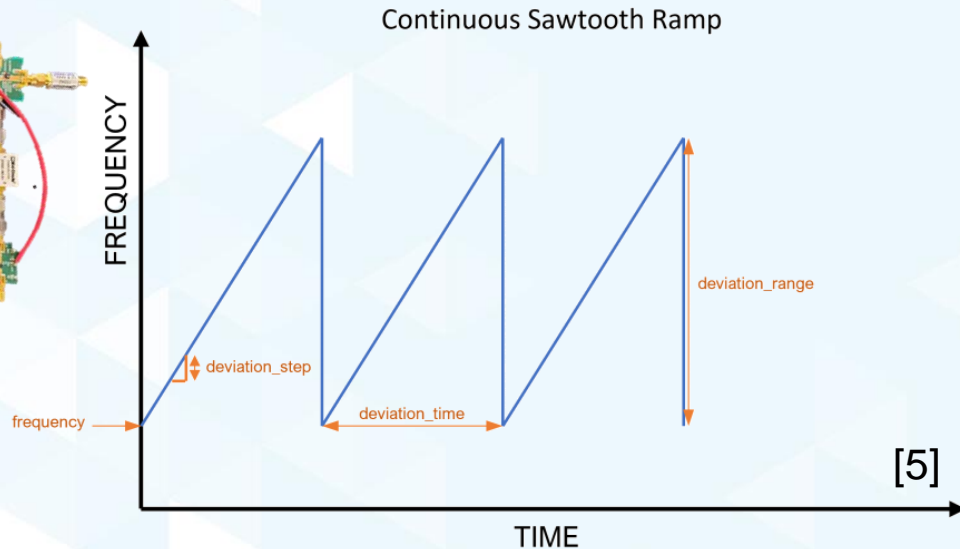
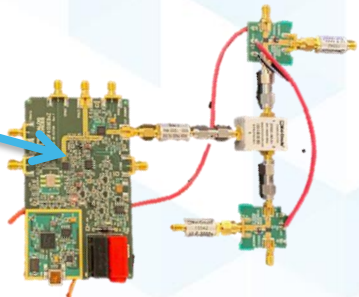
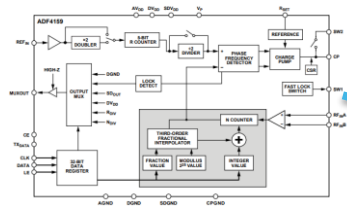
```
/sys/bus/iio/iio:device0 # cat name  
ad8366  
/sys/bus/iio/iio:device0 # echo 6 > out_voltage1_hardwaregain  
/sys/bus/iio/iio:device0 # cat out_voltage1_hardwaregain  
5.765000 dB
```

# ADF4159

Direct Modulation/Fast Waveform Generating, 13 GHz, Fractional-N Frequency Synthesizer



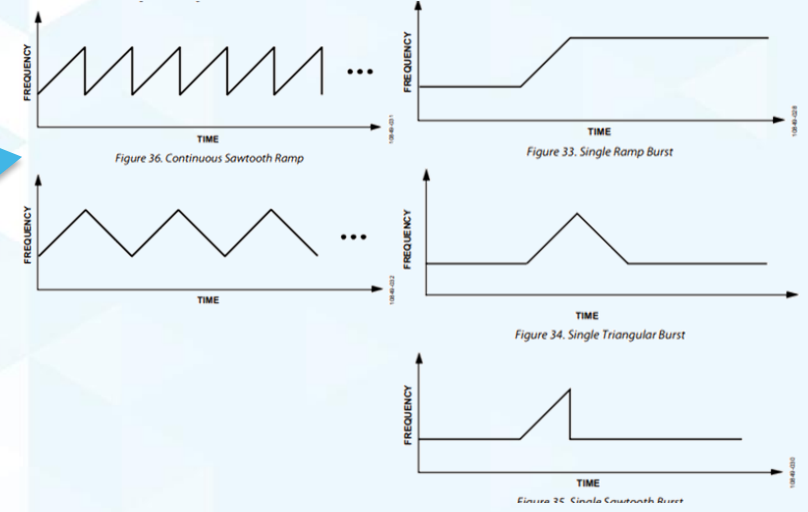
- dev
- name
- out\_altvoltage0\_frequency
- out\_altvoltage0\_frequency\_deviation\_range
- out\_altvoltage0\_frequency\_deviation\_step
- out\_altvoltage0\_frequency\_deviation\_time
- out\_altvoltage0\_powerdown
- out\_altvoltage0\_ramp\_mode
- out\_altvoltage0\_ramp\_mode\_available



## Shell Commands:

```

root@analog:~# iio_attr -c adf4159 altvoltage0
dev 'adf4159', channel 'altvoltage0' (output), attr 'frequency', value '6000000000'
dev 'adf4159', channel 'altvoltage0' (output), attr 'frequency_deviation_range', value '0'
dev 'adf4159', channel 'altvoltage0' (output), attr 'frequency_deviation_step', value '5960'
dev 'adf4159', channel 'altvoltage0' (output), attr 'frequency_deviation_time', value '0'
dev 'adf4159', channel 'altvoltage0' (output), attr 'powerdown', value '0'
dev 'adf4159', channel 'altvoltage0' (output), attr 'ramp_mode', value 'disabled'
dev 'adf4159', channel 'altvoltage0' (output), attr 'ramp_mode_available', value 'disabled continuous_sawtooth
continuous_triangular single_sawtooth_burst single_ramp_burst'
    
```

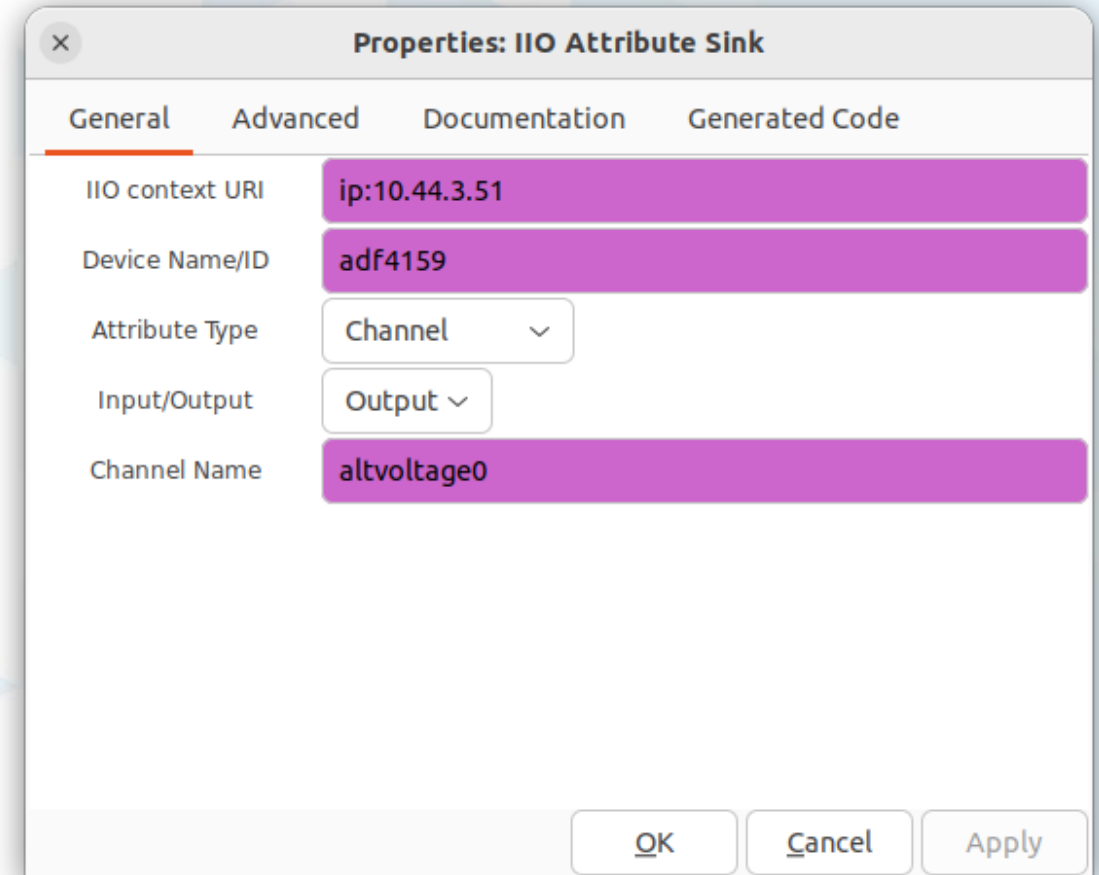




# iio\_attr\_sink

**IIO Attribute Sink**  
**IIO context URI:** ip:...4.3.51  
**Device Name/ID:** adf4159  
**Attribute Type:** Channel  
**Channel Name:** altvoltage0

- ▶ Generic writer for attributes of IIO devices.
- ▶ This block allow for updating of any IIO attribute that is writable. This includes channel, device, device buffer, device debug, and direct register attributes. All messages must be a **pmt dictionary** where the key is the attribute to update and the value is the value to be written. Messages can be an array of dictionaries or a single dictionary.



**Properties: IIO Attribute Sink**

General   Advanced   Documentation   Generated Code

IIO context URI: ip:10.44.3.51

Device Name/ID: adf4159

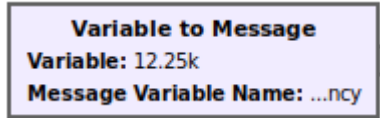
Attribute Type: Channel

Input/Output: Output

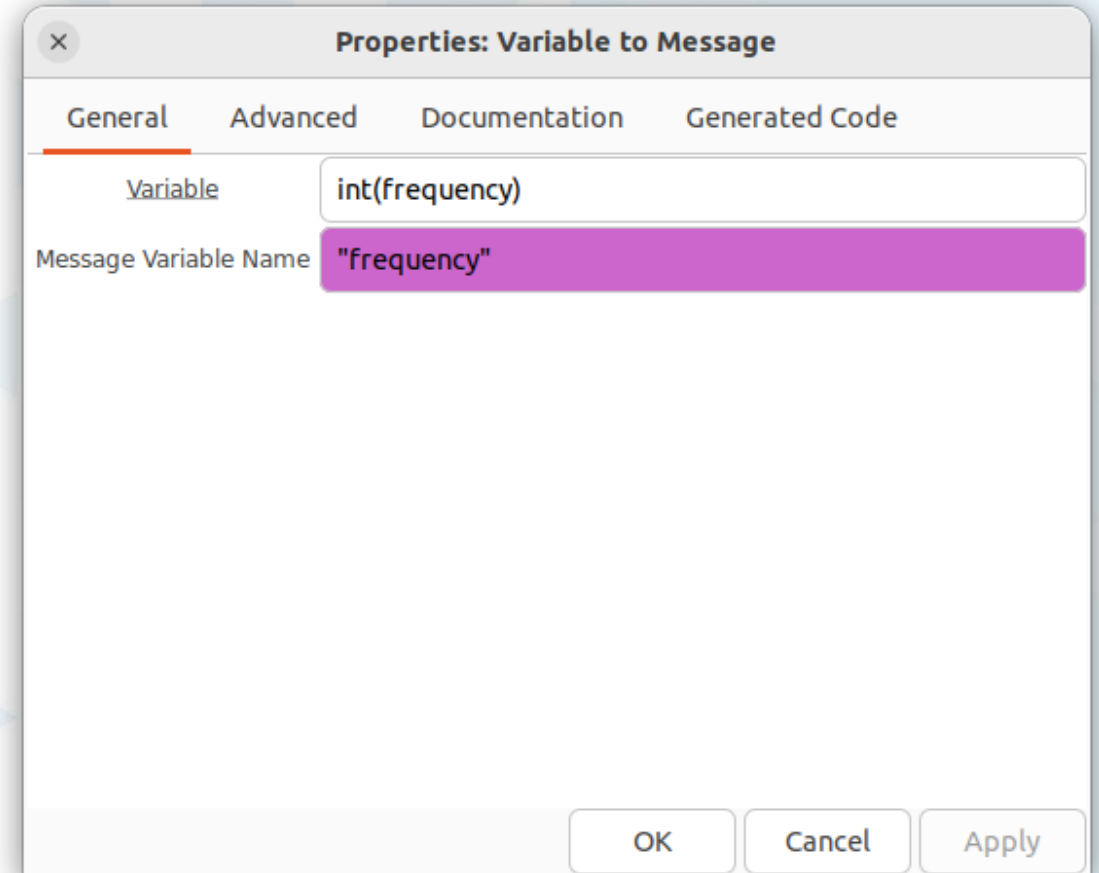
Channel Name: altvoltage0

OK   Cancel   Apply

# blocks\_var\_to\_msg (since 3.10)



- ▶ This block will monitor a variable, and when it changes, generate a message.
- ▶ This block has a callback that will emit a **message pair** with the updated variable value when called. This is useful for monitoring a GRC variable and emitting a message when it is changed.



# msg\_to\_iio\_dict (custom Python block)

**msg\_to\_iio\_dict**

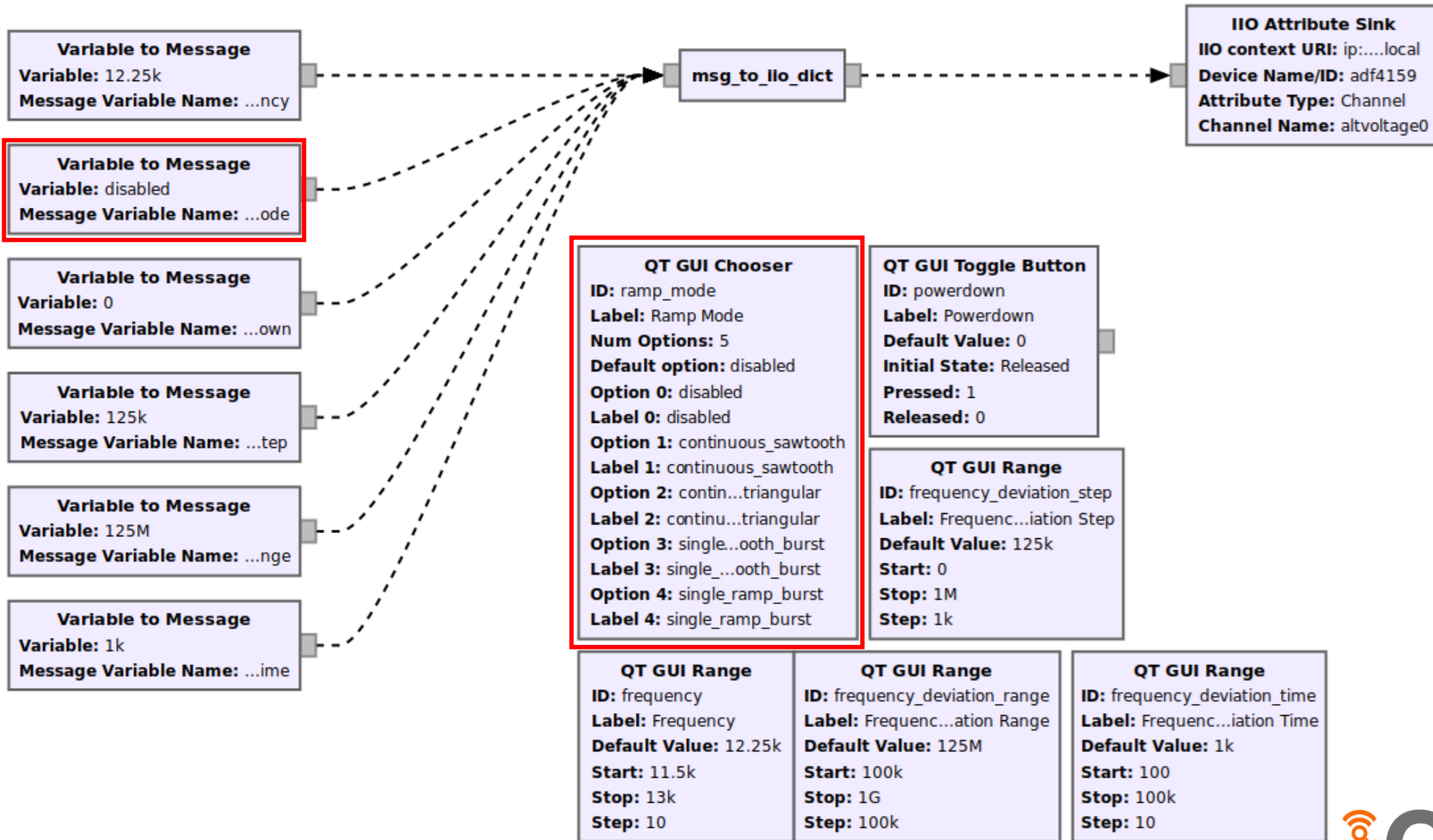
- ▶ Gr::basic\_block
- ▶ This block will convert a PMT message pair, into a PMT dictionary.
- ▶ Useful to interface the blocks\_var\_to\_msg with the iio\_attr\_sink block.

```
from gnuradio import gr
import pmt

class msg_block(gr.basic_block):
    def __init__(self):
        gr.basic_block.__init__(
            self,
            name="msg_to_iio_block",
            in_sig=None,
            out_sig=None)

        self.message_port_register_out(pmt.intern('msg_out'))
        self.message_port_register_in(pmt.intern('msg_in'))
        self.set_msg_handler(pmt.intern('msg_in'), self.handle_msg)

    def handle_msg(self, msg):
        nkey0 = pmt.intern(str(pmt.car(msg)))
        nval0 = pmt.intern(str(pmt.cdr(msg)))
        msg_dic = pmt.make_dict()
        msg_dic = pmt.dict_add(msg_dic, nkey0, nval0)
        self.message_port_pub(pmt.intern('msg_out'), msg_dic)
```



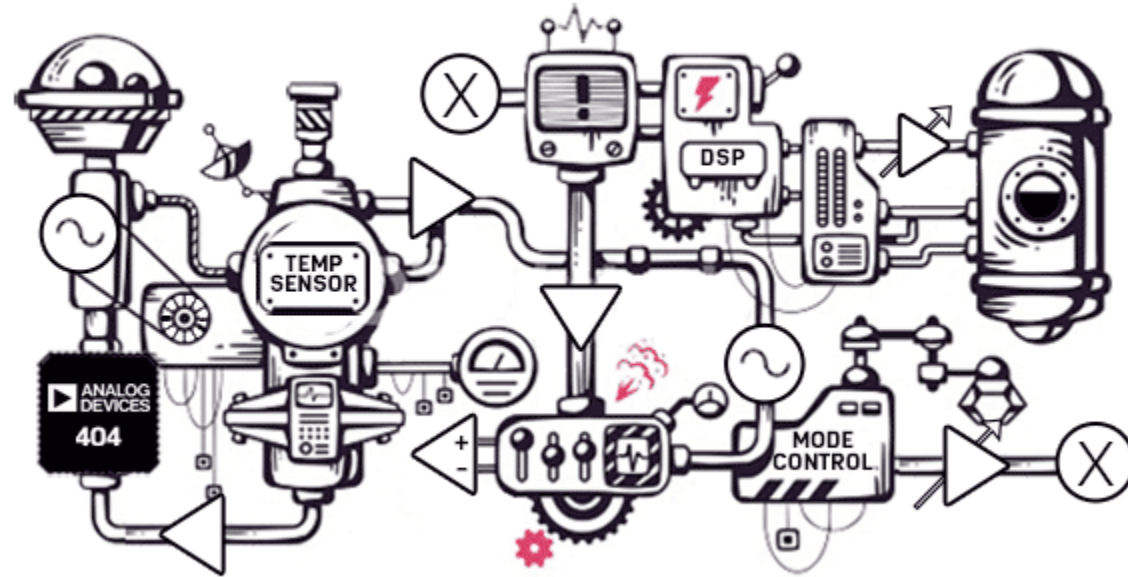


# Conclusions

- ▶ You don't need to be a Linux expert to enable and use ready made IIO drivers
- ▶ Gr-iio much more than controlling a transceiver/digitizer
- ▶ Gr-iio iio\_attr blocks should also accept PMT message pairs
  
- ▶ More interest in gr-iio and next generation libiio?
  - Latest libiio v0.24 also supports HWMON devices
  - Attend: Libiio 1.0 design and how it will affect GNU Radio, Paul Cercueil, 9/28/22
    - Multibuffer, Async Protocol, DMABUF compatible interface, Timestamp API (WIP)

# References

- [1] <https://www.analog.com/ad-fmcxmwr1-ebz>
- [2] <https://wiki.analog.com/resources/tools-software/linux-software/kuiper-linux>
- [3] <https://github.com/analogdevicesinc/linux/blob/rpi-5.10.y/arch/arm/boot/dts/overlays/rpi-adf4159-overlay.dts>
- [4] <https://github.com/analogdevicesinc/adi-kuiper-imager>
- [5] <https://wiki.analog.com/resources/tools-software/linux-drivers/iio-pll/adf4159>
- [6] <https://wiki.analog.com/resources/tools-software/linux-drivers-all>



Ahhh, technology. We can't find that page.

Thanks  
Q & A