

# GNU Radio Software Defined Radio University Project-Based Learning Using the Lime Mini SDR 2.0, Raspberry Pi 5.0

Application Focus: Multi-Hop Mesh Networks  
using the Cluster Duck Protocol

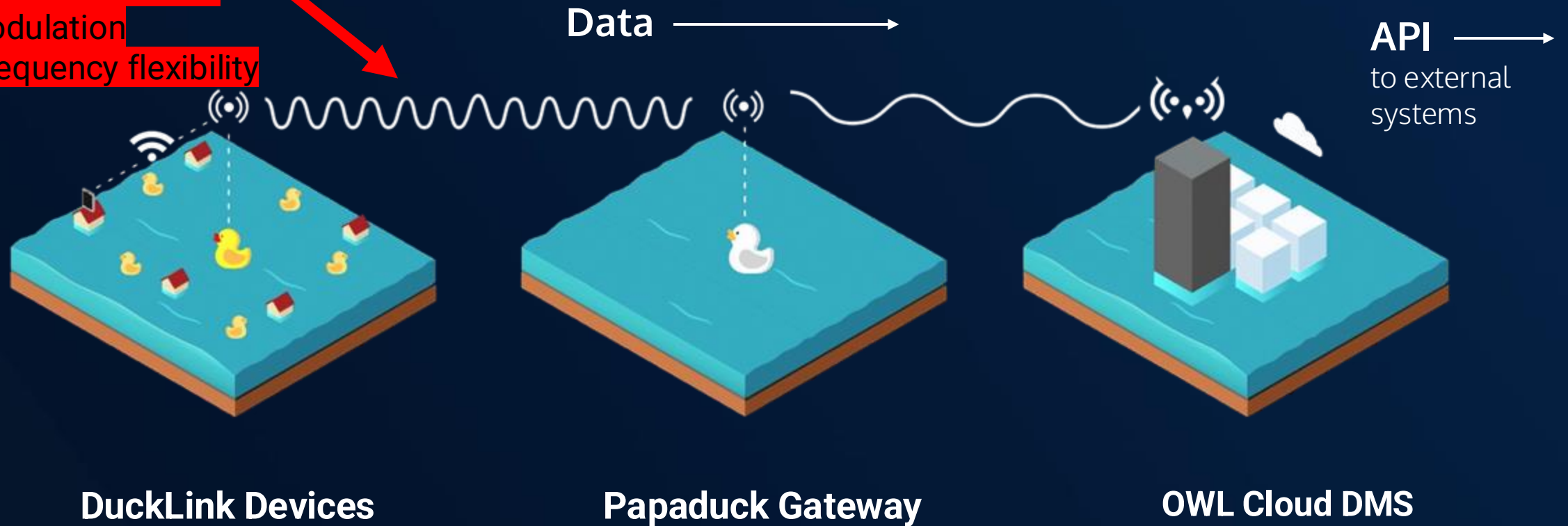
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Derickson

# Outline:

1. *GNU Radio Application Goal* – Physical Layer Flexibility for a Multi-Hop Mesh Network
2. EE504 Software Defined Radio Course – Spring 2024: Getting up to Speed with GNU Radio
3. Our Summer 2024 Efforts to incorporate GNU Radio with the Cluster Duck Protocol
4. Summary and Next Steps.

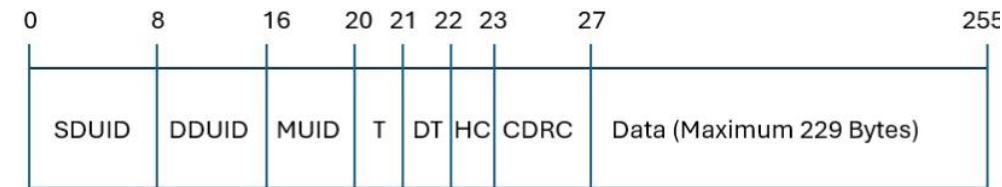
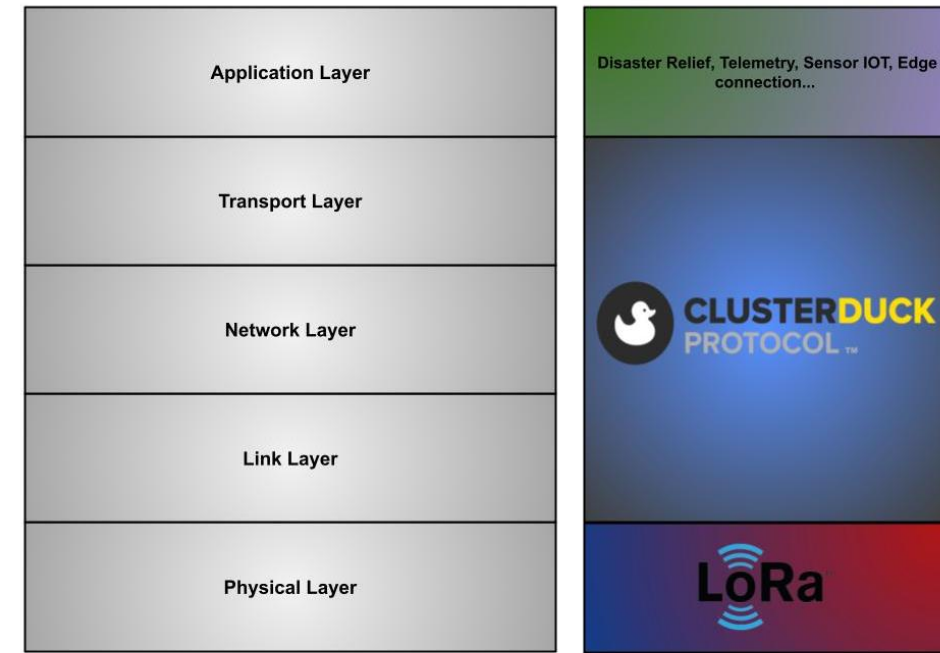
# GNU Radio Application Goal – Open-Source Multi-Hop Mesh Network using the Cluster Duck Protocol

USING LoRa NOW  
BUT WANT TO INCLUDE  
GNU Radio and SDRs  
for modulation  
and frequency flexibility



# OWL's Ducks – The Old and the New

- ▶ Started Cluster-Duck-Protocol to run "Duck" LoRa Mesh Network Radios  
<https://clusterduckprotocol.org>
- ▶ A single CDP Packet fits into the LoRa payload
- ▶ Open source CDP Software, DIY radios:  
<https://github.com/ClusterDuck-Protocol/ClusterDuck-Protocol>
- ▶ Sponsored a Senior Project which turned into Summer Research using LimeSDR + Raspberry Pi



Parameter	Number of Bytes	Data Type	Description
SDUID	08	Byte Array	Source Device Unique ID
DDUID	08	Byte Array	Destination Device Unique ID
MUID	04	Byte Array	Message Unique ID
T	01	Byte Value	Topic
DT	01	Byte Value	Duck Type; 0=Duck Link 1= MamaDuck 2= PapaDuck
HC	01	Byte Value	Hop Count (The number of times that the packet was relayed)
DCRC	04	Byte Value	Data Section Cyclical Redundancy Code
Data	229	Byte Array	Data Payload (could be sensor data or any type of text)

# Open-Source Hardware and Software for the Cluster Duck Protocol Network and Our Vision for the "QuAD Pro"

QuAD R1 vs.

QuAD RC1 vs.

QuAD RC2 vs.

QuAD-PRO



Rev 1 Based on current electronics solution, custom packaging and software.

- GPS
- LORA
- WiFi
- Cluster Duck Protocol (CDP)
- Existing Development
- Ongoing Feature additions

QUAD RC1 Based on RP Boards

- GPS
- LORA
- WiFi
- Cluster Duck Protocol (CDP)
- In Progress
- First Hardware early spring quarter 24
- Rev 2 planned for Fall Quarter

QUAD RC2 Based on TI Board

- GPS
- LORA
- WiFi (on processor)
- Cluster Duck Protocol (CDP)
- hardware security features
- In Progress
- First Hardware late spring quarter 24
- Rev 2 planned for fall quarter

QUAD Pro Project

- GPS
- LORA
- WiFi (on processor)
- Cluster Duck Protocol (CDP)
- improved processing power
- video capable
- frequency and modulation agile
- edge network machine learning
- In Definition and prototyping stage
- First Hardware theorized late Spring Quarter 2024

**THIS IS THE FOCUS OF OUR EFFORT FOR GNU RADIO**

# Provided Hardware used for Senior Project, EE504 and Summer Research

EE504



Lime Mini 2.0 SDR



Raspberry Pi 5 kit



GPS  
Module +  
Antenna

Summer Research,  
QuAD Pro



Raspberry Pi  
Camera



SX1262 LoRa  
Module



Monitor + Keyboard  
Setup



Test equipment:  
Tiny SA, Analog  
Discovery II. Test  
Coax cables and  
attenuators



Old  
generation  
Ducks  
(SX1276)

Additional Testing  
Hardware

# Software used, provided or found

GNU Radio Companion: <https://www.gnuradio.org>

DragonOS Raspberry Pi Image:  
<https://sourceforge.net/projects/dragonos-pi64/>

LoRa Out of Tree Module: [https://github.com/tapparelj/gr-lora\\_sdr](https://github.com/tapparelj/gr-lora_sdr)

LimeSuite: <https://github.com/myriadr/LimeSuite/>  
LimeSuiteNG: <https://github.com/myriadr/LimeSuiteNG/>



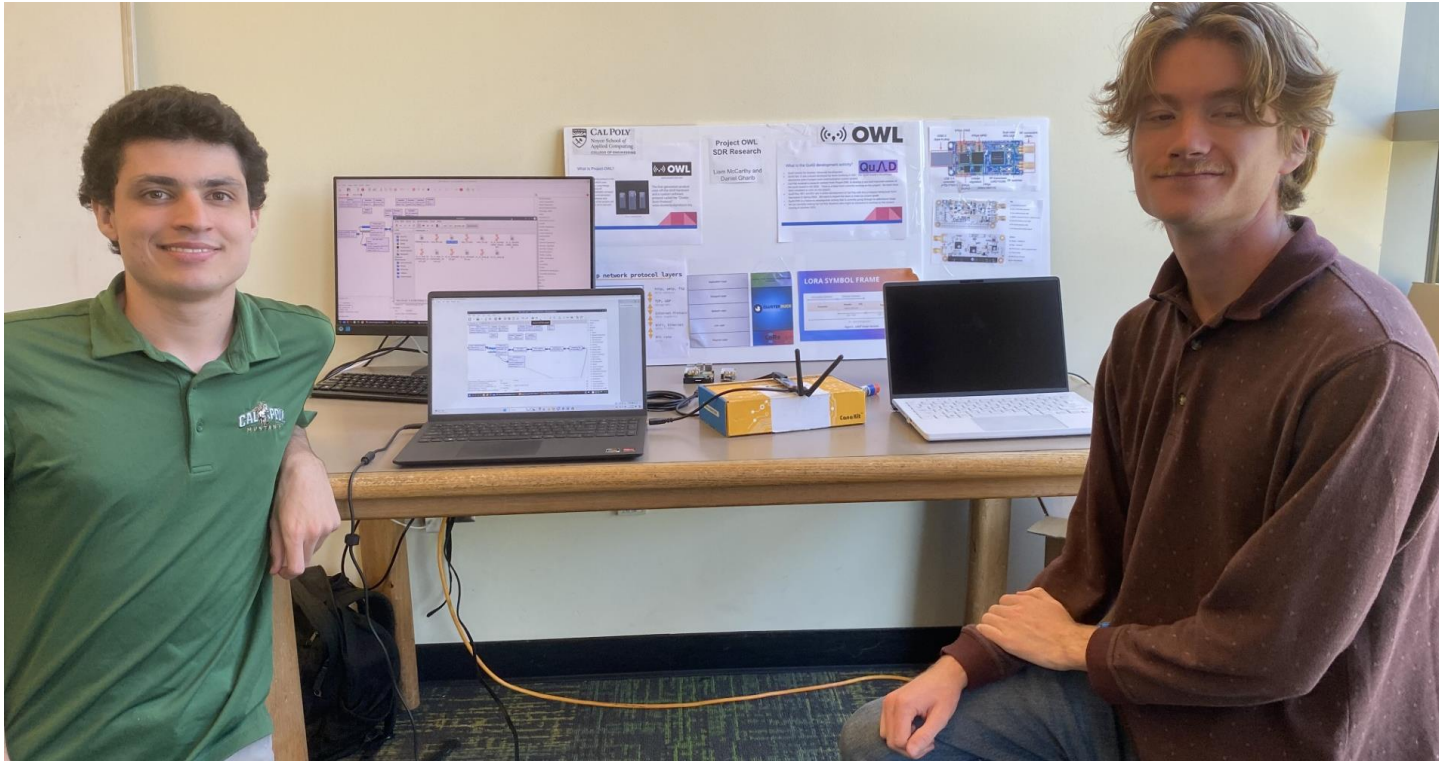
# LimeSDR Mini 2.0 Pros/Cons

Pros	Cons
Wide frequency range	Limited output power
Highly configurable in GNU Radio without modifying FPGA	Requires good foundation of SDR understanding.
Small, Easy to transport and use in field.	Requires a lot of USB power under some situations.
Semi-affordable	Complex for beginners. Not easy to get started with as of 2024
Active software support, "next gen" LimeSuite	Current software currently does not work for LimeSDR Mini 2.0, no built-in GR 3.10 OOT Modules
SoapySDR Support for GR3.10	Not ideal for a dedicated solution to one modulation



# Our Introduction to GNU Radio with the LimeSDR Mini 2.0

- ▶ Senior Project: **Exploration of Software Defined Radios in Mesh Networks**

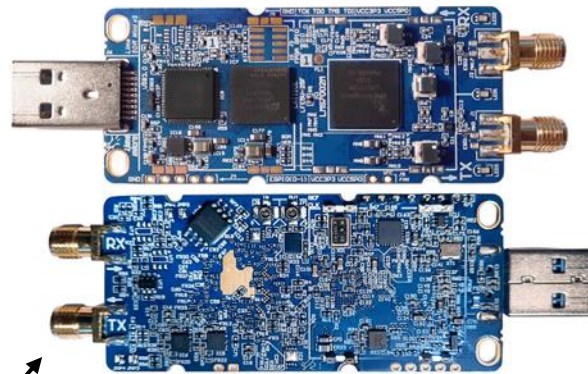


- ▶ Tasked with exploring using Software Defined Radios on a theoretical Raspberry Pi Computer-based radio and pathfinding uses of the LimeSDR 2.0

Question: How do I learn to use my Lime Mini 2.0 and GNU Radio *quickly*

Answer 1: Go to the wiki tutorials!

Answer 2: Also volunteer to TA and develop GNU Radio Lessons for EE504: Software Defined Radio Laboratory



Getting Lime Mini 2.0 Working on my Pi:

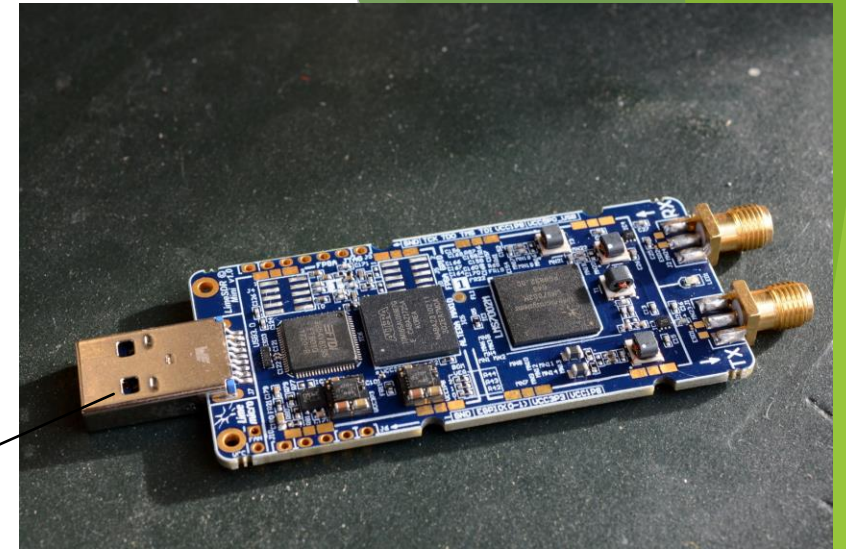
- First Step
- Took way longer than expected



Needed DragonOS to be successful and to be able to quickly get students onboarded

# EE504 - Software Defined Radio Lab

- ▶ Students started with exposure to ADALM-PLUTO and MATLAB from another TA, more in line with lecture topics
- ▶ Transitioned to learning GNU Radio in lab ~Week 6, giving 5 weeks to learn GNU Radio and produce a unique final project



# Approach to Introducing GNU Radio to EE504 Lab

Get everyone's hardware working.  
LimeSDR needs to pass its self-test

```
File Actions Edit View Help
liam@liam-VirtualBox: /usr/src/gr-lora_sdr/test
1DA1442D54CDEE, Hw=7, Gm=2.2
Warning: USB3 not available
Serial Number: 1DA1442D54CDEE
Chip temperature: 48 c

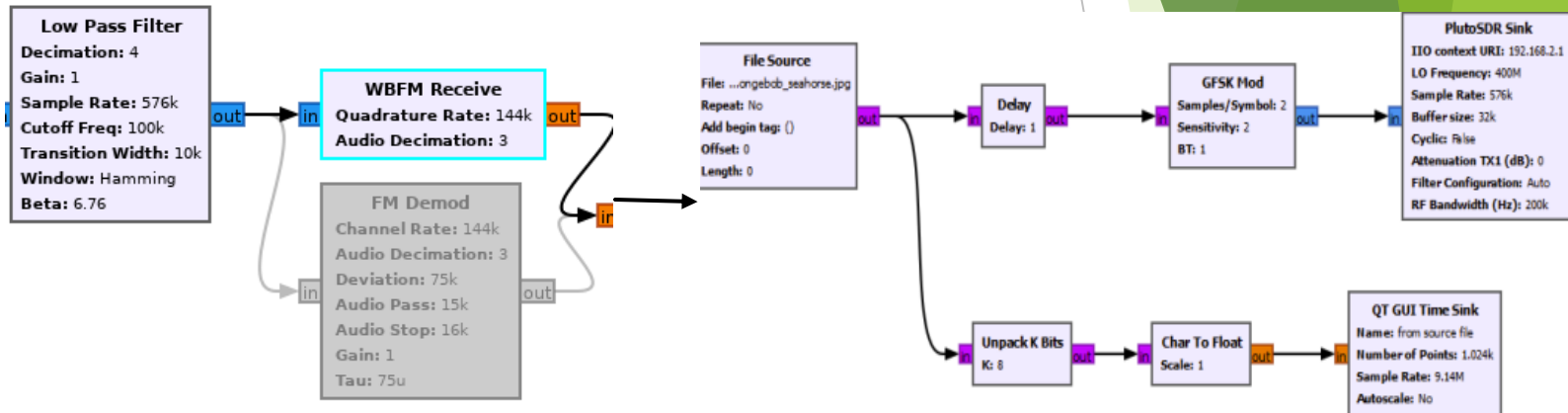
[ Clock Network Test ]
->REF clock test
Test results: 46896; 49826; 52649 - PASSED
->VCTCXO test
Results : 6711037 (min); 6711075 (max) - PASSED
->Clock Network Test PASSED

[ FPGA EEPROM Test ]
->Read EEPROM
FPGA EEPROM not supported in v2
->FPGA EEPROM Test PASSED

[ LMS7002M Test ]
->Perform Registers Test
->External Reset Line test
Reg 0x20: Write value 0xFFFD, Read value 0xFFFD
Reg 0x20: Value after reset 0xFFFD
->LMS7002M Test PASSED

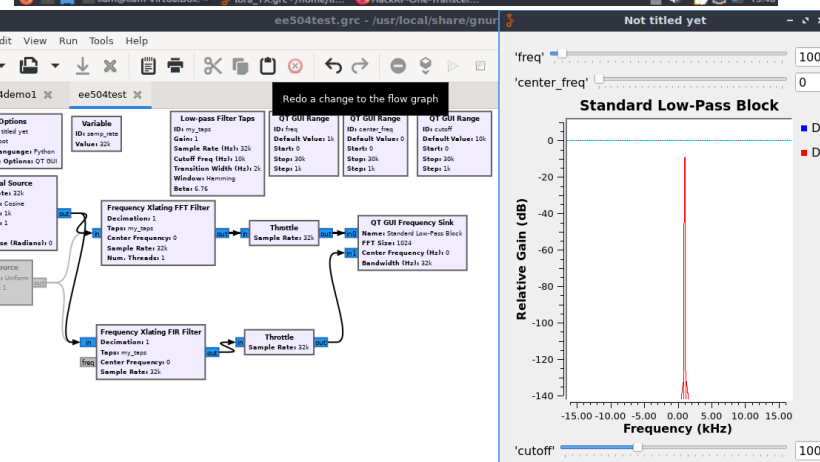
[ RF Loopback Test ]
->Configure LMS
->Run Tests (TX_2 -> LNA_W):
CH0 (5XR=2100.0MHz, SXT=2105.0MHz): Result:(-29.8 dBFS, 5.00 MHz) - PASSED
->Run Tests (TX_1 -> LNA_H):
CH0 (5XR=2100.0MHz, SXT=2105.0MHz): Result:(-26.4 dBFS, 5.00 MHz) - PASSED
->RF Loopback Test PASSED

=> Board tests PASSED ==
```



Have students work up to simple Modulators, Demodulators

Assist students with more advanced topics and their final projects



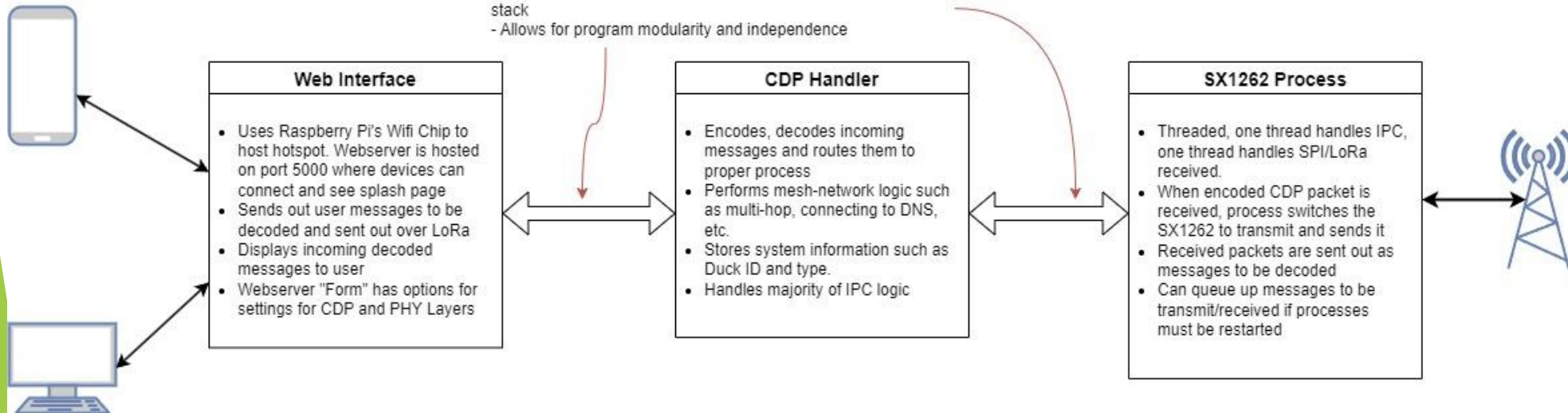
Start with very basic simulated flowgraphs to introduce concepts and blocks

# The QuAD Pro Prototype

- ▶ 3 separate processes run at the same time, each loosely representing one part of the "CDP Stack"
- ▶ Uses Redis, a simple IPC, to communicate between processes using message streams. Messages are queued up for tasks to complete to handle multiple messages
- ▶ Using separate processes with a defined IPC format allows us to in the future replace the "PHY Process" with a proces that can select and run flowgraphs

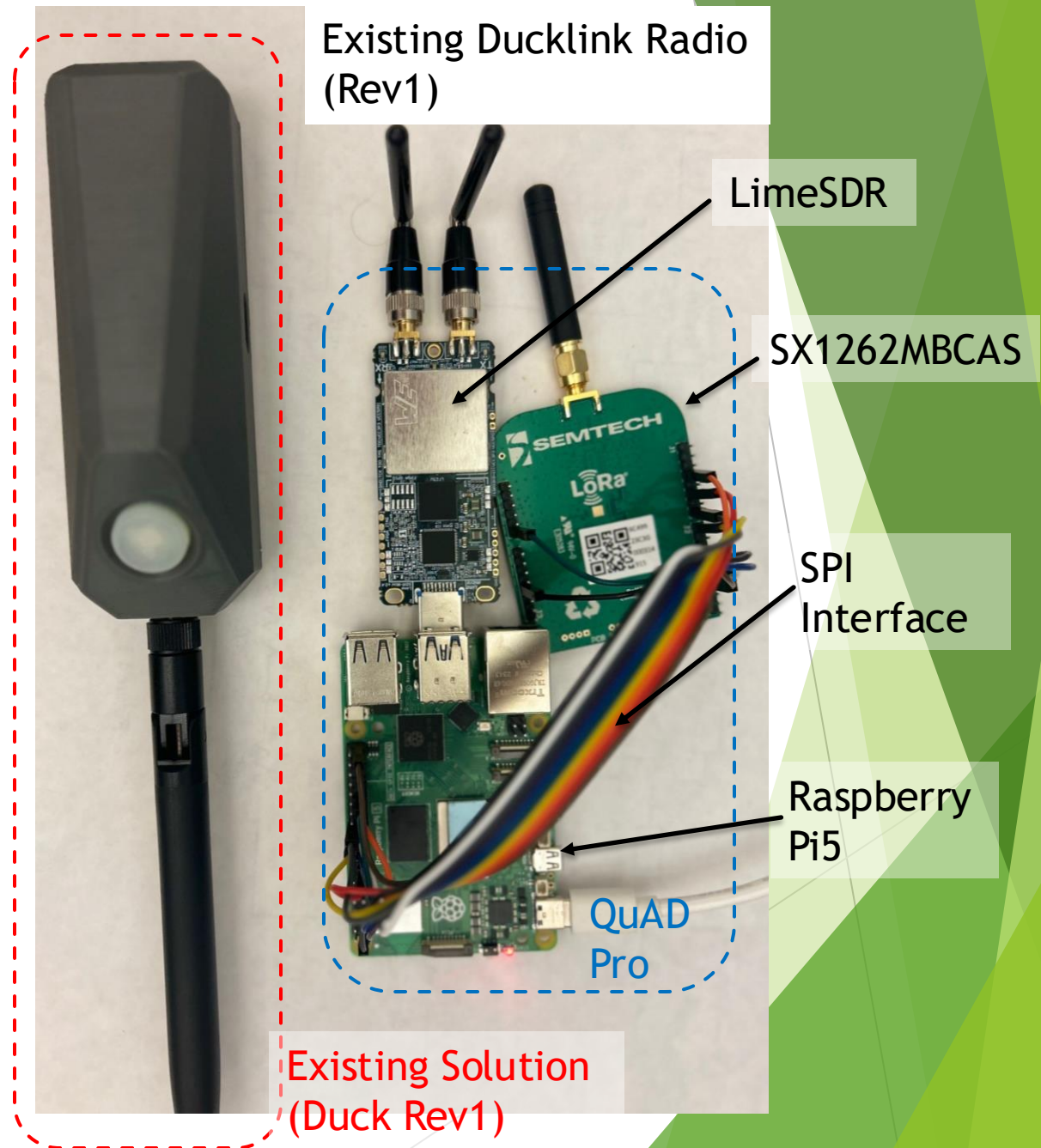
## Redis Streams

- Used for Inter-Process Communication
- Broke 3 processes up along the lines of the 3 layers of CDP stack
- Allows for program modularity and independence



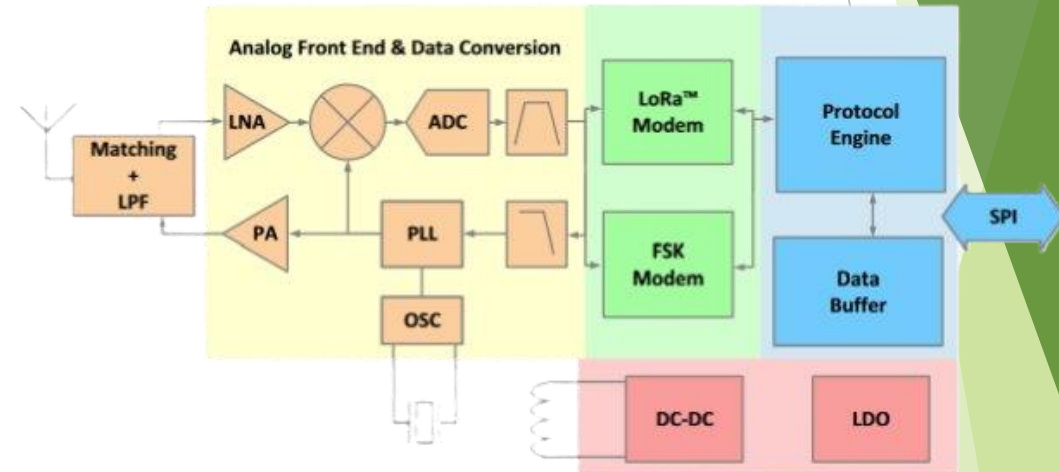
# GNU Radio for QuAD Pro Summer Research

- ▶ Prototype "QuAD Pro" Software developed and in debugging phase: (QuAD pro github)
  - SX1262 Driver, Hotspot + Web-server and CDP Packet code all written by students
  - Efforts in the 10-week program were to make a basic system others can debug, improve, and eventually use with SDR applications
- ▶ Preliminary "Robustness" and "Reliability" tests comparing SDR to old and new Semtech SX1276, SX1262 Transceivers.
- ▶ Improvement of LoRa and FSK Flowgraphs to minimize weaknesses and open up potential interfacing to other processes



# SX1262 LoRa and FSK Transceiver

- Dual modem transceiver (LoRa/FSK).
  - Frequency range: **150 - 960 MHz**.
  - Data rate: FSK **300kbps**, LoRa **62.5kbps**
  - Max RF Output Power **22 dBm**
  - Low power consumption
- **Objective:** Compare the reliability and performance of SX1262 and LimeSDR Mini 2.0 using FSK/LoRa modulation across configurable parameters.



SX1262 Block Diagram

Source: [Semtech Corporation, SX1262 Datasheet, \[Datasheet\]](#)

# LoRa and FSK Through GNU Radio - Can SDR compete with the SX1262

- **Why Compare FSK & LoRa on SDR vs. SX1262?**
  - **Application:** Both have been proposed to be used on QuAD Pro
  - **Flexibility:** Can SDR quickly change LoRa/FSK parameters like the SX1262?
  - **Dedicated Performance:** SX1262 is hardware-optimized, how does SDR stack up?
  - **Real-World vs. Emulated Results:** Practical insights into differences in reliability and use cases
- **Expectations:**
  - **SDR:** Adaptable, great for testing and prototyping but more likely to be susceptible to noise or demodulate incorrectly.
  - **SX1262:** Tuned for efficiency and real-world applications, much more power efficient than SDR. Likely to take slightly longer to set up even with given code than SDR





# SDR Flowgraph vs New Duck Transceiver vs Old Duck Transceiver

- ▶ Bit Error Rate and Packet Drop frequency are our two main points to compare
- ▶ Each hardware set is going to be slightly different

## SX1276: (LoRa only)

- ▶ Onboard Rev1 Duck, meaning code is run on a T-Beam board
- ▶ Outdated board doesn't work with newest ESP Drivers -> RadioLib Doesn't work -> FSK not possible. Used other LoRa library

## SX1262:

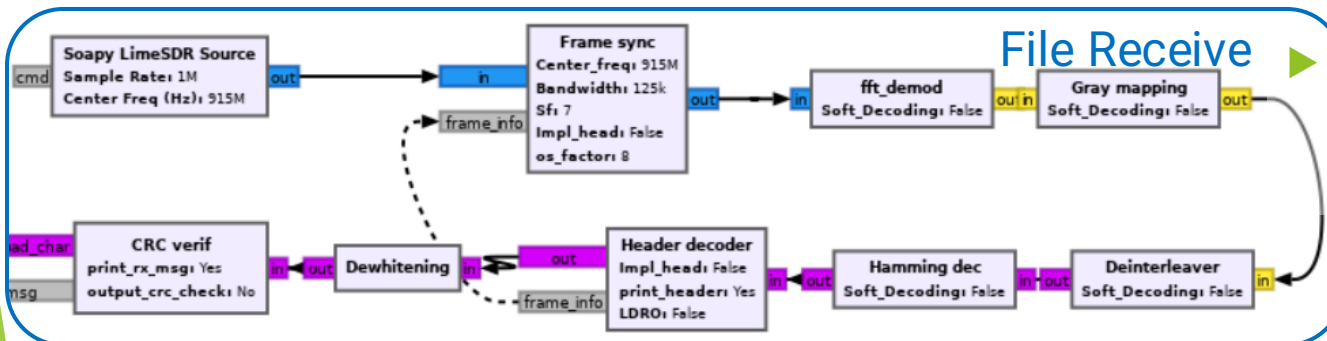
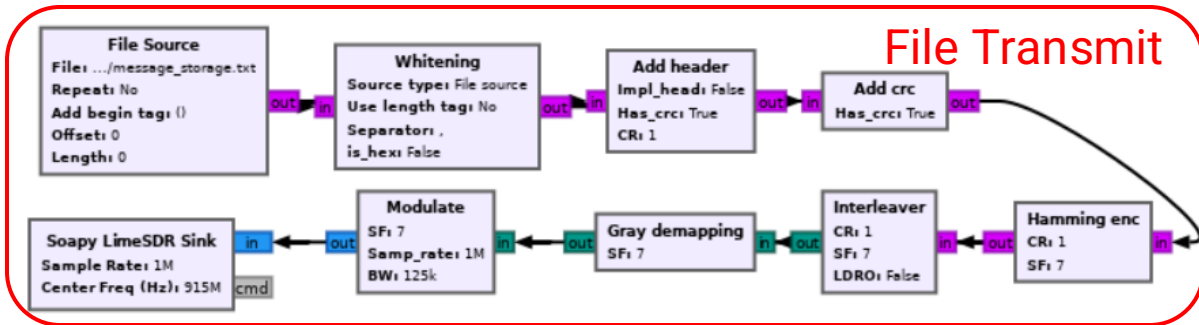
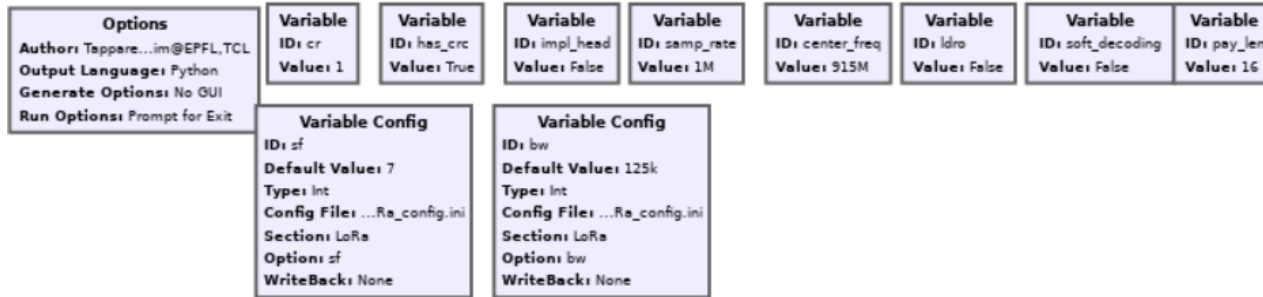
- ▶ Uses GPIO pins of Raspberry Pi 5, WiringPi to control
- ▶ Also uses RadioLib with custom HAL code. Can compare FSK

## SDR:

- ▶ USB Port of Raspberry Pi 5, requires drivers on DragonOS image (or proper version of LimeSuite)
- ▶ Flowgraphs can differ from true PHY, ability to add functionality not possible with Semtech Transceiver



# LoRa on GNU Radio – gr-lora\_sdr



- ▶ All true LoRa blocks were built by tapparelj: [https://github.com/tapparelj/gr-lora\\_sdr](https://github.com/tapparelj/gr-lora_sdr). Probably wasn't going to be able to do this myself with <2 months of GNU Radio experience
- ▶ Originally built flowgraphs for Senior Project to encode+decode CDP packets with custom blocks. Limited success due to packet corruption and perhaps SX1276 timing
- ▶ Added blocks for more advanced file read/write options. Added config file to be used for semi-automated testing.

# FSK Modulator/Demodulator



```
self.samp_rate = samp_rate
self.fsk_deviation = fsk_deviation
self.center_freq = 0
self.phase_inc0 = 2.0 * np.pi * (self.center_freq - self.fsk_deviation) / self.samp_rate
self.phase_inc1 = 2.0 * np.pi * (self.center_freq + self.fsk_deviation) / self.samp_rate
self.phase = 0

def work(self, input_items, output_items):
    out = output_items[0]
    in0 = input_items[0]

    # Process the input data
    if len(in0) > 0: # Check for data
        for i in range(len(in0)):
            if in0[i] == 0:
                self.phase += self.phase_inc0
            else:
                self.phase += self.phase_inc1
            out[i] = np.exp(1j * self.phase)
            if self.phase > 2.0 * np.pi:
                self.phase -= 2.0 * np.pi
    else:
        print("Received empty input data") # no data

    return len(out)
```



```
class fsk_demod(gr.sync_block):
    def __init__(self, samp_rate=1e6, fsk_deviation=500e3):
        gr.sync_block.__init__(
            self,
            name='FSK Demodulation',
            in_sig=[np.complex64],
            out_sig=[np.int8]
        )
        self.samp_rate = samp_rate
        self.fsk_deviation = fsk_deviation

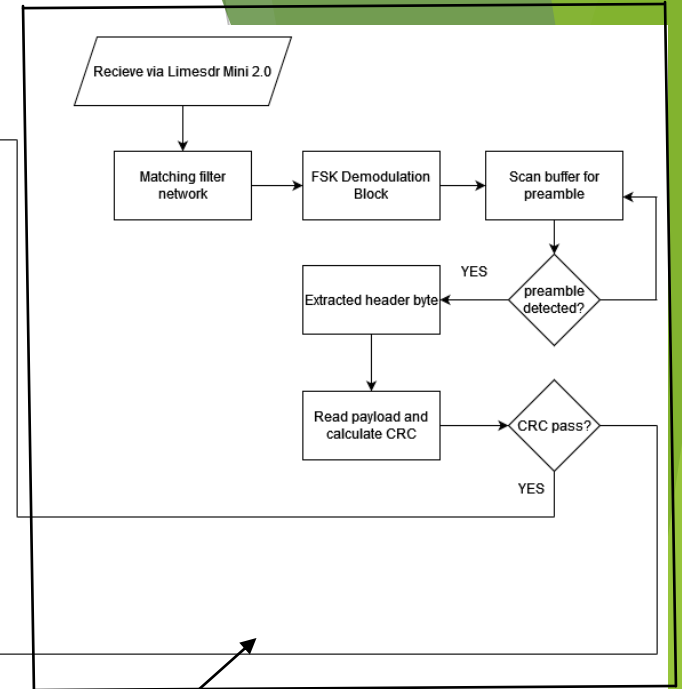
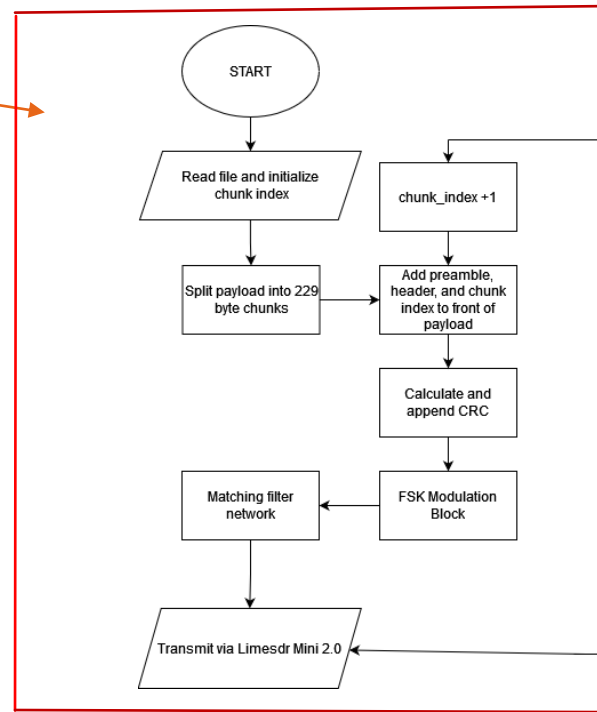
    def work(self, input_items, output_items):
        in0 = input_items[0]
        out = output_items[0]

        for i in range(1, len(in0)):
            phase_diff = np.angle(in0[i] * np.conj(in0[i-1]))
            out[i] = 1 if phase_diff > 0 else 0
        return len(output_items[0])
```

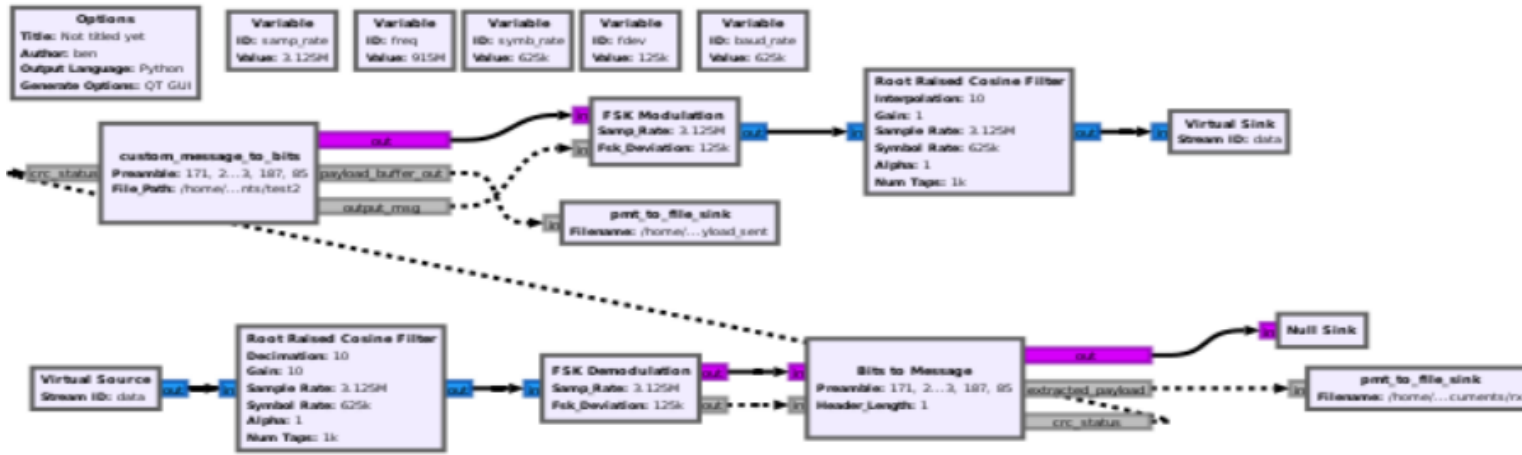
# FSK on Gnu Radio

- ▶ Implemented a packet based system establishing a link between 2 LimeSDR mini-2.0s using FSK modulation.
- ▶ A CRC is calculated and used as our basic check if a packet is transmit and received correctly

TX



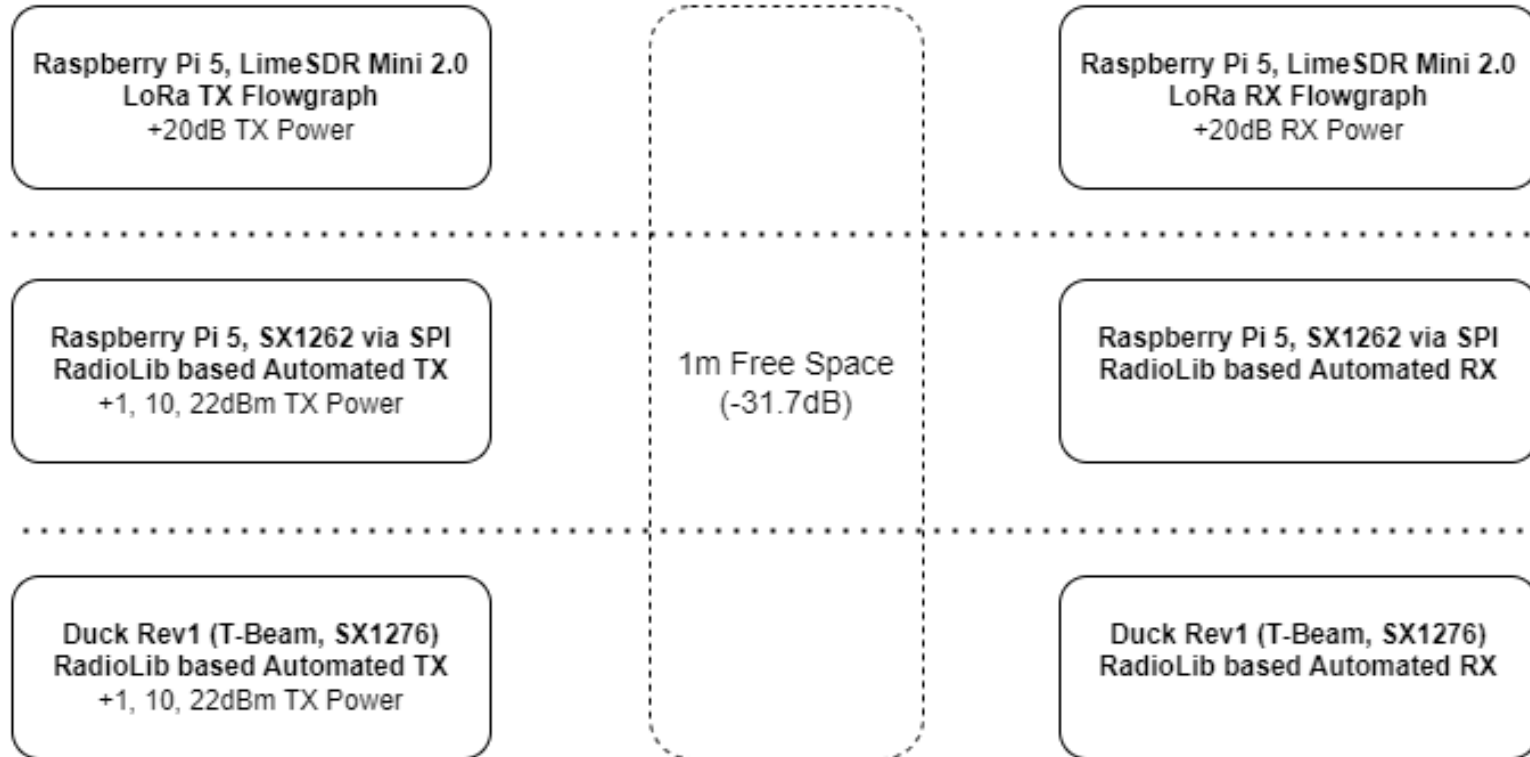
RX



# Testing setup LoRa

## Parameters Tested

SF: 7, 9, 11  
BW: 62.5, 125, 250, 500kHz  
CR: 5, 8



# Testing setup FSK

## Parameters Tested

BitRate: 4.8, 9.6, 19.2, 76.8, 153.6kbps  
Freq. Deviation: 10, 25, 50, 75, 100kHz

Raspberry Pi 5, LimeSDR Mini 2.0  
FSK Packet TX Flowgraph  
+20dB TX Power

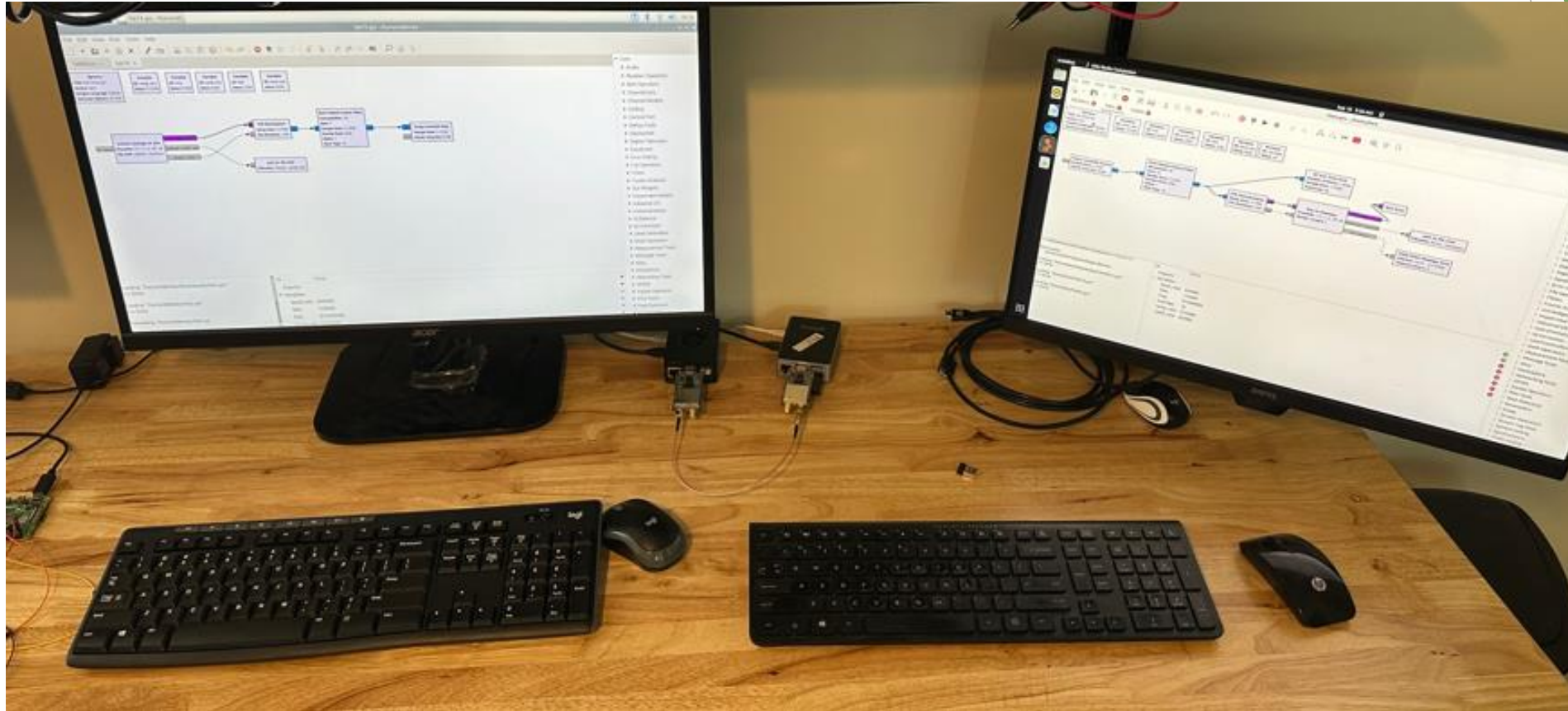
Raspberry Pi 5, LimeSDR Mini 2.0  
FSK Packet RX Flowgraph  
+20dB RX Power

1m Free Space  
(-31.7dB)

Raspberry Pi 5, SX1262 via SPI  
RadioLib based Automated TX  
+5, 10, 20dBm TX Power

Raspberry Pi 5, SX1262 via SPI  
RadioLib based Automated RX

# Testing setup



# LoRa Performance Comparisons

## Notes:

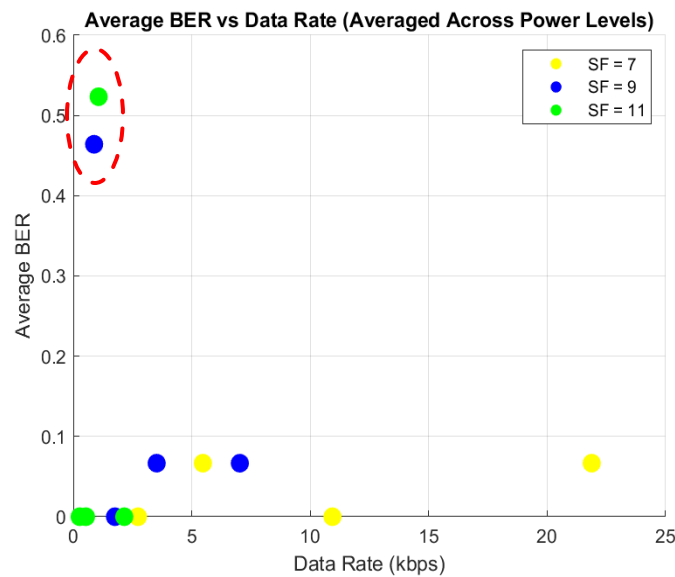
- Experienced abnormally high error rates/packet losses at extremely low data rates
- LoRa OOT module is restricted. "Requires too many taps" for extremely low data rate demodulation, I.E. these could not be compared with dedicated LoRa transceivers

## SX1276/SX1262:

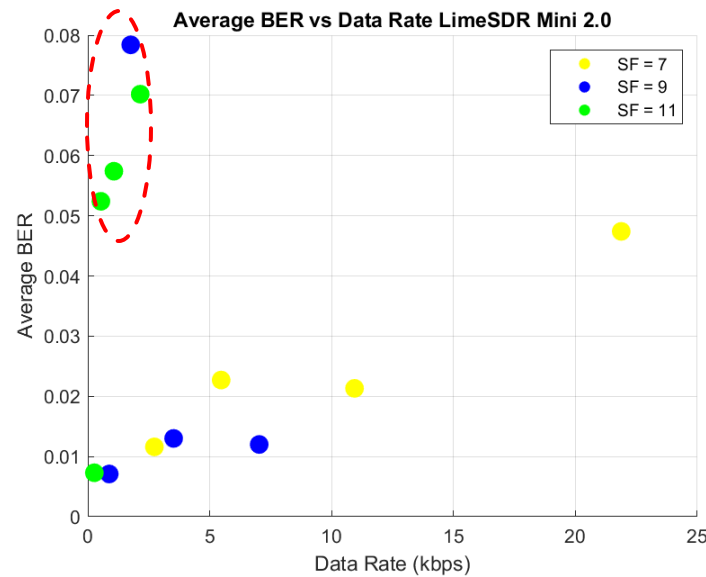
- Similar "low data rate problem" on both modules
- When packets were properly received, the SX1262 performed better in bit errors. More packets dropped led to the seemingly worse performance

## Lime Mini 2:

- Consistent performance, much more susceptible to noise and gain settings
- Bit errors are to be expected unless settings are "perfect"



SX1262



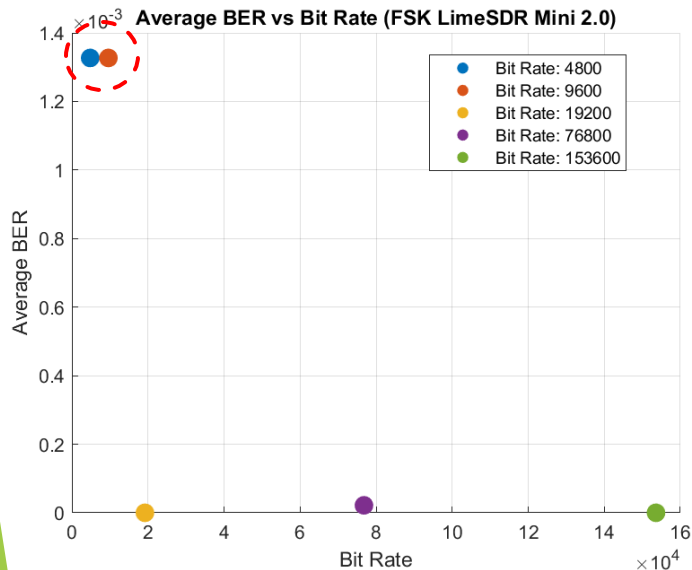
Lime Mini 2



# FSK Performance Comparisons

## Performance at Lower Bit Rates (4.4 kbps-76kbps)

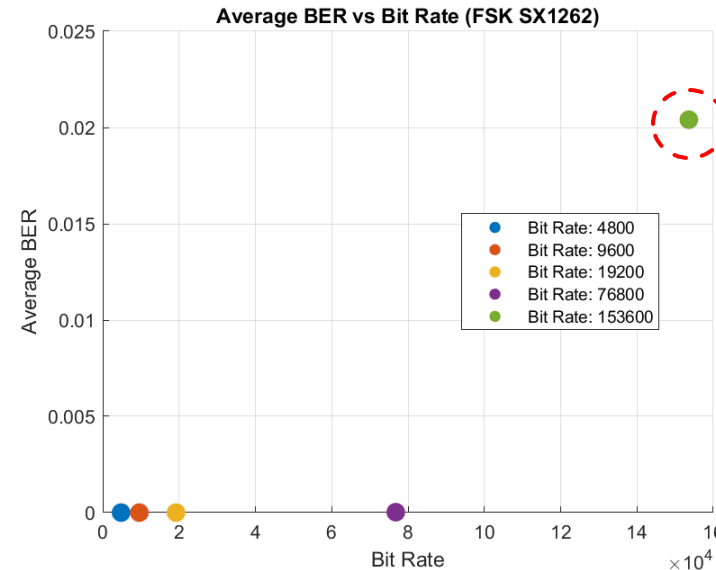
- **SX1262:**
  - **PER:** 0%
  - **BER:** 0%
  - **Reliability:** Excellent, error-free communication at low data rates.
- **GNU Radio LimeSDR Mini 2.0:**
  - **PER:** 2.94%
  - **BER:** 0.13%
  - **Reliability:** Consistent performance, moderate error rate.



SX1262

## Performance at Higher Bit Rates (153.6 kbps+)

- **SX1262:**
  - **PER:** Increases up to 4% at 20 dBm at Fdev of 10kHz.
  - **BER:** Increases up to 9.84%.
  - **Challenge:** Significant errors, less reliable at high bit rates.
- **GNU Radio LimeSDR Mini 2.0:**
  - **PER:** Consistent 2.94% across all configurations.
  - **BER:** Typically, 0.00% to 0.13%.
  - **Advantage:** Maintains steady performance even at higher bit rates.



Lime Mini 2

# Summarizing Results

Code used for all tests and results can be found in "tests" folder on our GitHub: <https://github.com/limccart7/GRCon-Project>

## **"Old" 1276:**

- Could not test FSK because of older hardware compatibility issues
- Not as frequency/parameter agile as newer chip

## **SX1262:**

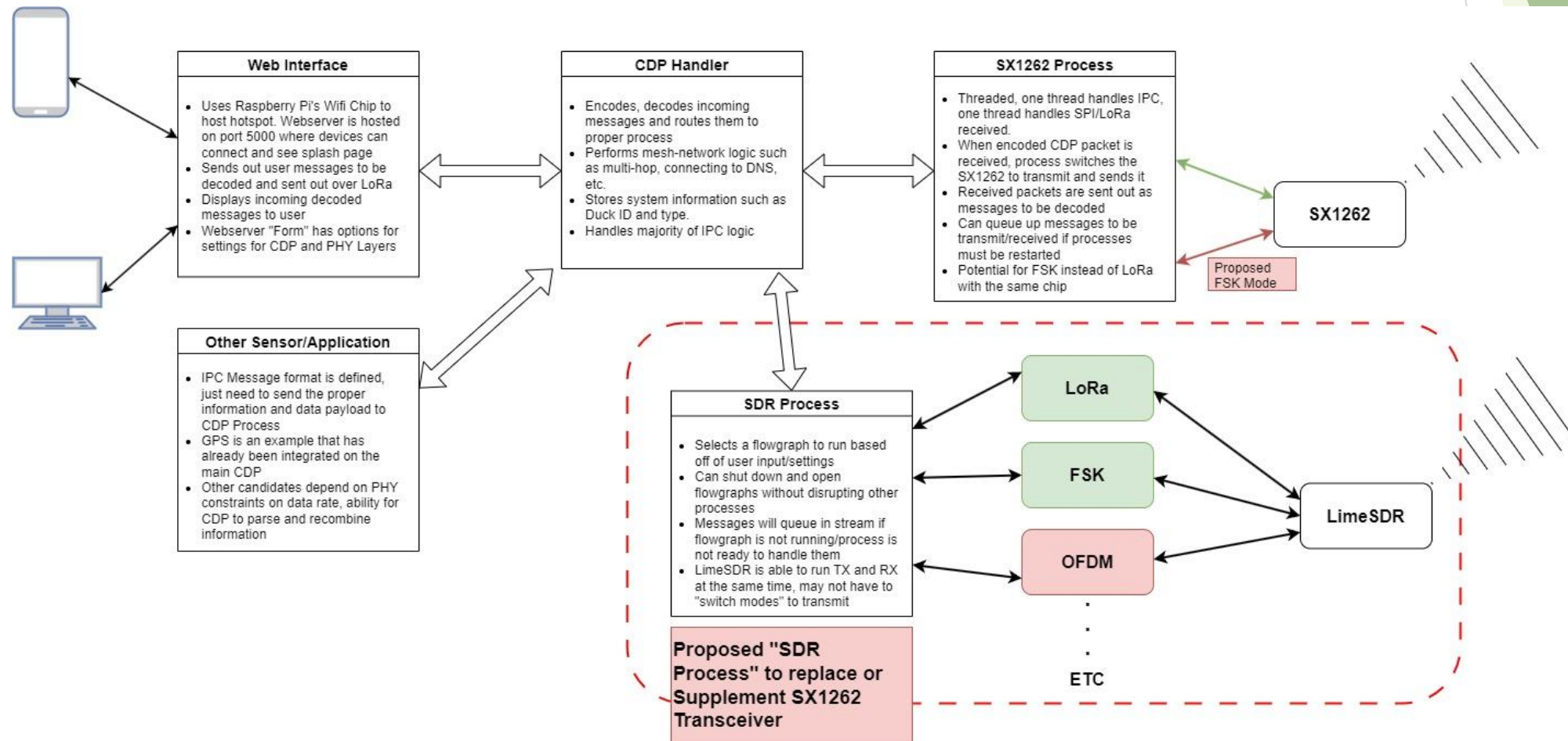
- Best performance in terms of BER and packets dropped
- Using Raspberry Pi GPIO pins made setup, interacting with the chip slightly more difficult

## **Lime Mini 2:**

- Not ideal for "high end" situations, higher BER and much more likely to drop packets
- Flowgraphs give us the ability to retransmit on CRC check failure, other ways of mitigating shortcomings

# Future Work - A Frequency and Modulation Agile Transceiver for Raspberry Pi/QuAD Pro

- ▶ Use "QuAD Pro" Prototype's Inter-Process-Communication to integrate SDR Flowgraphs with ClusterDuck Protocol
- ▶ Develop a program that configures the parameters of flowgraphs and starts them. Eventual goal is to have a system that can quickly change its modulation and parameters based off user input





Questions

# Links, Further Reading

- Our GitHub, again: <https://github.com/limccart7/GRCon-Project>
- Main QuAD Pro Prototype Summer Research: <https://github.com/limccart7/QuAD-Pro-Prototype>

## References:

- <https://clusterduckprotocol.org>
- [https://github.com/tapparelj/gr-lora\\_sdr](https://github.com/tapparelj/gr-lora_sdr)
- <https://cemaxecuter.com> (DragonOS)